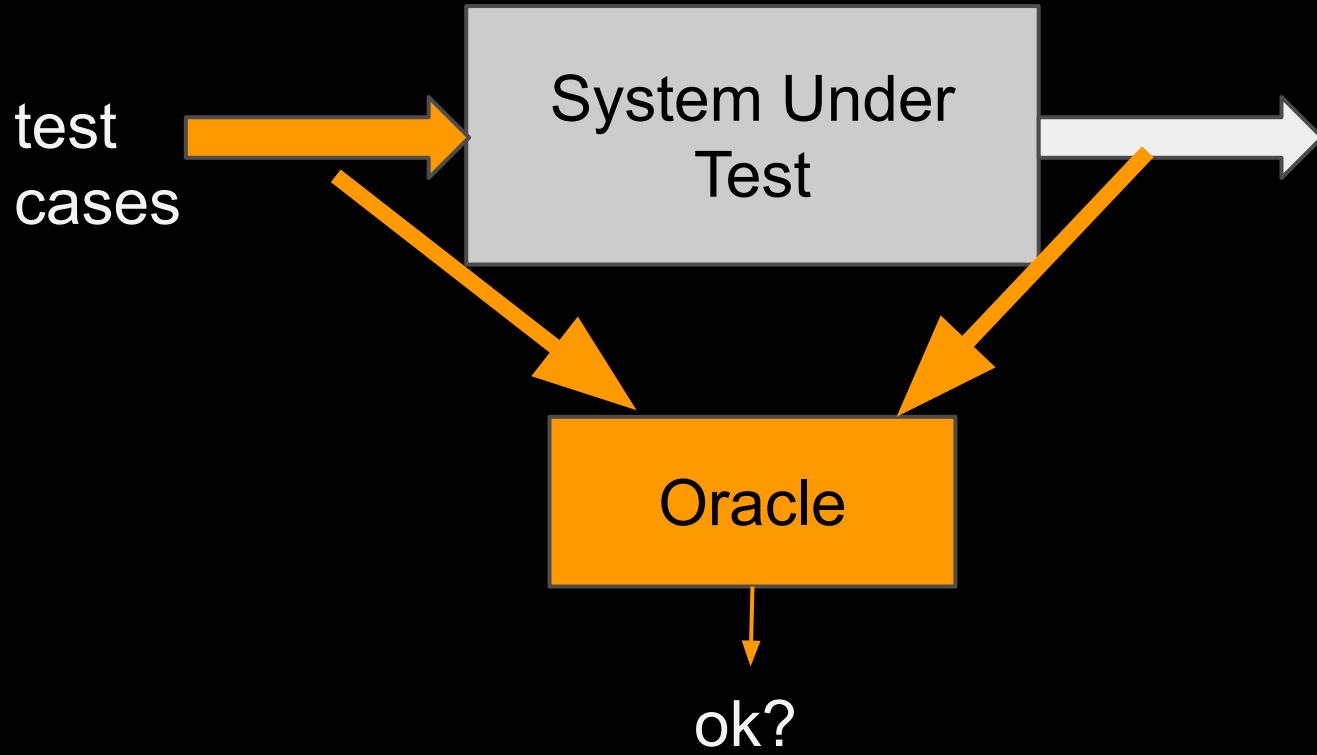


# **Inductive Testing**

**with applications to  
compiler/interpreter testing**

Koen Claessen  
Chalmers University of Technology  
and Epic Games



# Test Oracle: 3 Principles

- 1. Simple
  - Simpler than the implementation
- 2. Efficiently runnable
  - May need to run many tests
- 3. “Completeness”
  - For any faulty implementation, there should exist inputs that trigger the oracle to say “no”

# **Example:**

# **Shortest Path Algorithms**

```
type Map  
type Point  
type Path
```

```
shortest : (Map, Point, Point) -> Maybe Path
```

```
( solve : Problem -> Maybe Solution )
```

# Problem

- The oracle needs to know what the shortest path is
- We can be **simple**, but it is **too slow**
  - Not practical when testing
  - (Non-termination!)
- We can be **fast**, but it is **too complex**
  - We may not trust our test results

# Property-based Testing

(a la QuickCheck)

**Sound** - If an answer is produced, it should be an actual solution

**Complete** - If no answer is produced, there indeed was no actual solution

**Optimal** - If an answer is produced, there is no actual solution that is better



**Sound** - If an answer is produced, it should be an actual solution

easy to test  
(simpler)

**Complete** - If no answer is produced, there indeed was no actual solution

hard to test  
(oracle copies implementation)

**Complete** - If no answer is produced, there indeed was no actual solution

logically equivalent

**Complete'** - If there is a solution, some answer will be produced

testable

ForAll x .  $A(x) \implies B(x)$

ForAll x in “A”.  $B(x)$

ForAll mp,a,b .  
 hasPath mp a b ==>  
 isJust (shortest (mp, a, b))

produce a map, two  
points, and a path  
between those points

ForAll mp,a,b in hasPathMap .  
 isJust (shortest (mp, a, b))

**Optimal** - If an answer is produced, there is no actual solution that is better

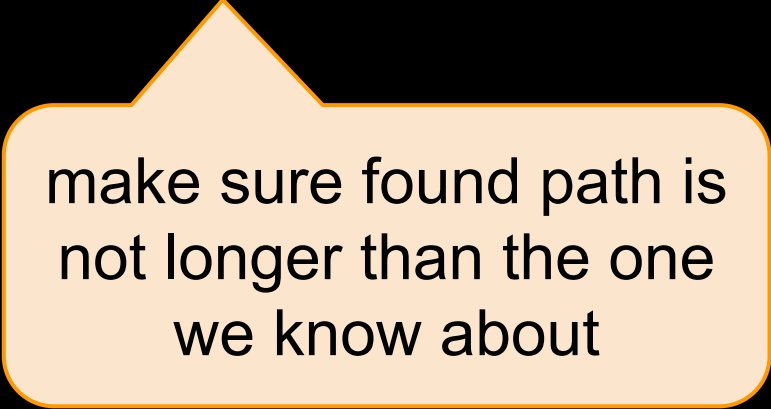
logically equivalent

**Optimal'** - If there is a solution, then no worse answer will be produced

testable!

ForAll mp,a,b in hasPathMap .

**let** Just path = shortest (mp, a, b) **in**  
length path <= length hasPathMap



make sure found path is  
not longer than the one  
we know about

# Contrapositive testing

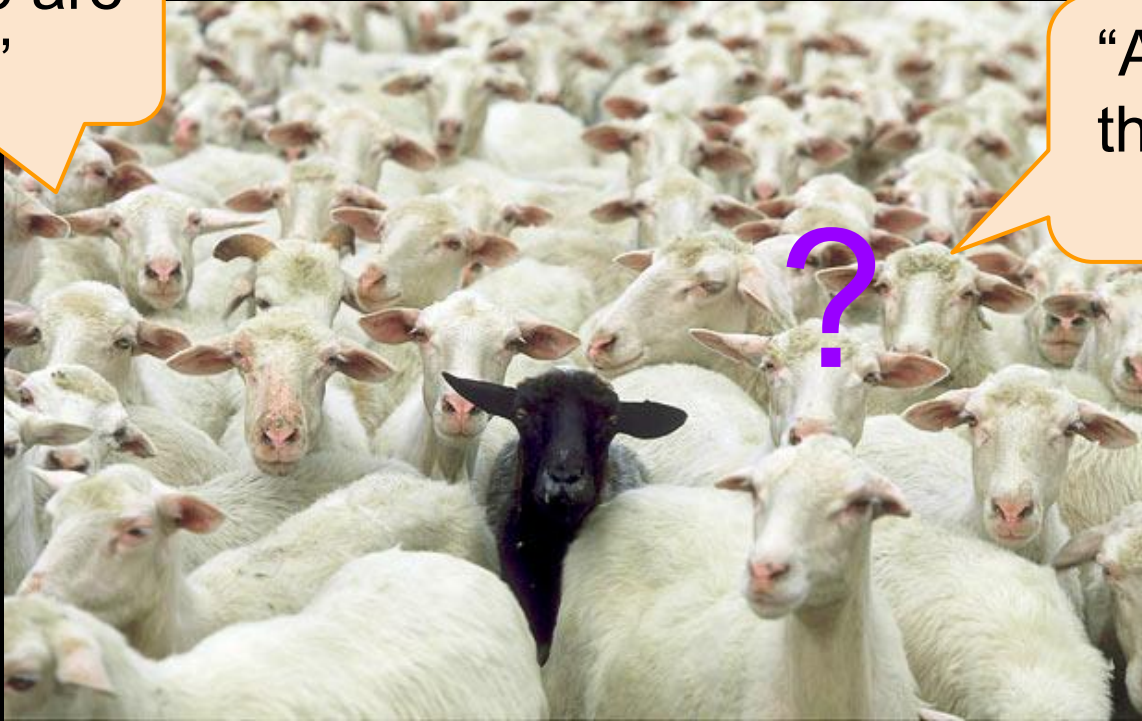
- Change your viewpoint
  - From: Stimuli / System Under Test / Oracle
  - To: Proofs / Logical implication
- And take the **contrapositive** view to get new inspiration



# Contrapositive Testing

“All sheep are white”

“All non-white things are not sheep”



# **Shortest Distance Algorithms**

```
type Map
```

```
type Point
```

```
data Distance = Inf | Fin Int
```

```
distance : (Map, Point, Point) -> Distance
```

hard!

**Sound** - If an answer is produced, it should be an actual solution

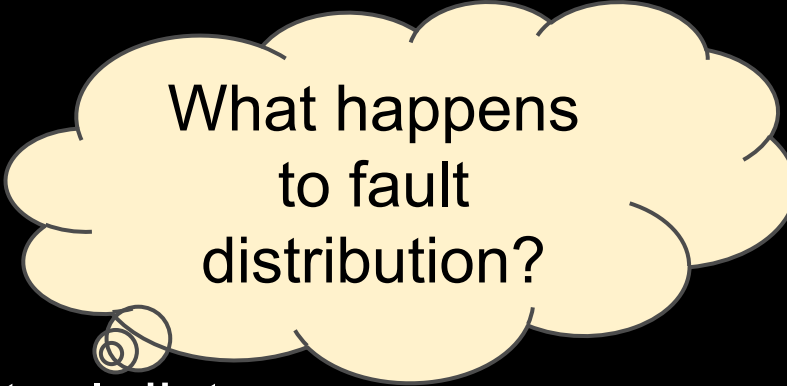
**Complete** - If no answer is produced, there indeed was no actual solution

**Optimal** - If an answer is produced, there is no actual solution that is better

```
ForAll mp,a .  
  distance(mp,a,a) == Fin 0
```

```
ForAll mp,a,b .  
  distance(mp,a,b) ==  
    minimum [ distance(mp,a',b) + d  
              | (a',d) <- neighbors(mp,a)  
              ]
```

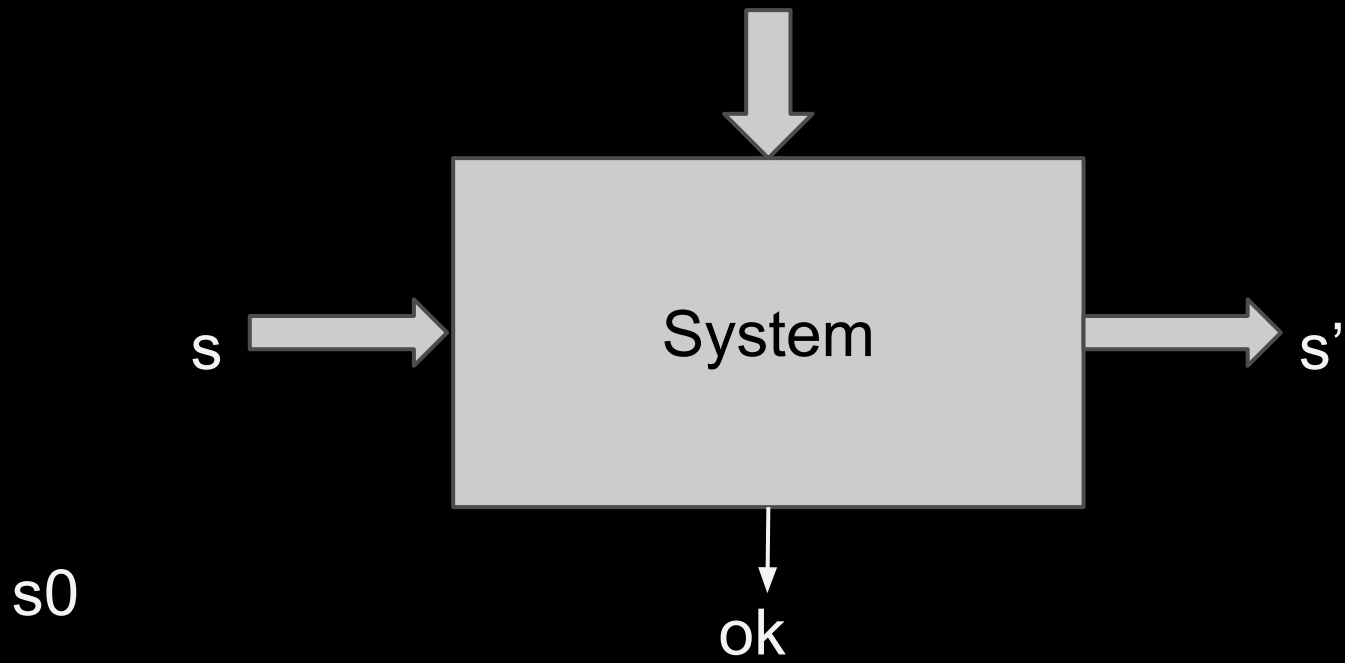
# Inductive Testing



What happens  
to fault  
distribution?

- Correctness: by induction
  - soundness: induction over actual distance
  - completeness: induction over function answer
- Induction principle
  - choose this for enabling testing
  - independent of implementation (unlike proving)

# Testing Model Checkers for Safety Properties





check : (State, Circuit) -> Bool

False: The system is  
**not safe**; often  
produces a **trace**

True: The system is **safe**;  
(produces nothing)

$\text{step} : (\text{State}, \text{System}, \text{Input}) \rightarrow (\text{Bool}, \text{State})$

```
safe(s, S) =  
  ForAll inp .  
    let (ok, s') = step(s, S, inp) in  
      ok && safe(s', S)
```

greatest fixpoint

$\text{step} : (\text{State}, \text{System}, \text{Input}) \rightarrow (\text{Bool}, \text{State})$

ForAll  $s, S$  .

$\text{check}(s, S) \Rightarrow$

        ForAll  $\text{inp}$  .

**let**  $(\text{ok}, s') = \text{step}(s, S, \text{inp})$  **in**  
                 $\text{ok} \ \&\& \ \text{check}(s', S)$

- Correctness

- Safety is defined as *greatest fixpoint*
- Most natural is to use *coinduction*

$$a \leq F(a)$$

---

$$a \leq \text{gfp } x . F(x)$$

- Efficiency

- Model checker is called twice for each test

# Proof-based Testing: contrapositive testing, inductive testing, coinductive testing

- Break away from the oracle view
- Look at the **logical meaning** of the property
- Use proof techniques to “break up” into smaller properties
  - Together, they imply the original property
  - They may be easier to test
  - The system may be run several times
- What happens to the distribution of faulty test cases?

# **Inductive Testing of Compilers/Interpreters with QuickCheck**

```
data Program
  = Var := Expr
  | Skip
  | Program :>>: Program
  | IfThenElse Expr Program Program
  | Decl Var Program
  ...
```

```
compileAndRun :: Program -> State -> IO State
```

“differential  
testing”

```
compileAndRun2 :: Program -> State -> IO State
```

```
prop_CompilersSame :: Program -> State -> IO Bool
prop_CompilersSame p s1 =
  do s2 <- compileAndRun p s1
      s2' <- compileAndRun2 p s1
      return (s2 == s2')
```

```
> quickCheck prop_CompilersSame
*** FAILED (after 17 tests and 13 shrinks):
if y then
  var x in y := 0
else
  skip
```

minimal  
counter  
example



**Library**  
for writing  
test data generators

recursive  
generators

specify  
frequencies  
for the cases

keep track of  
test data sizes

keep track of  
invariants

**Library**  
for writing 1-step  
shrinking functions

## Library

for writing 1-step  
shrinking functions

replace a part with  
an immediate  
sub-part

*for free*

custom rules

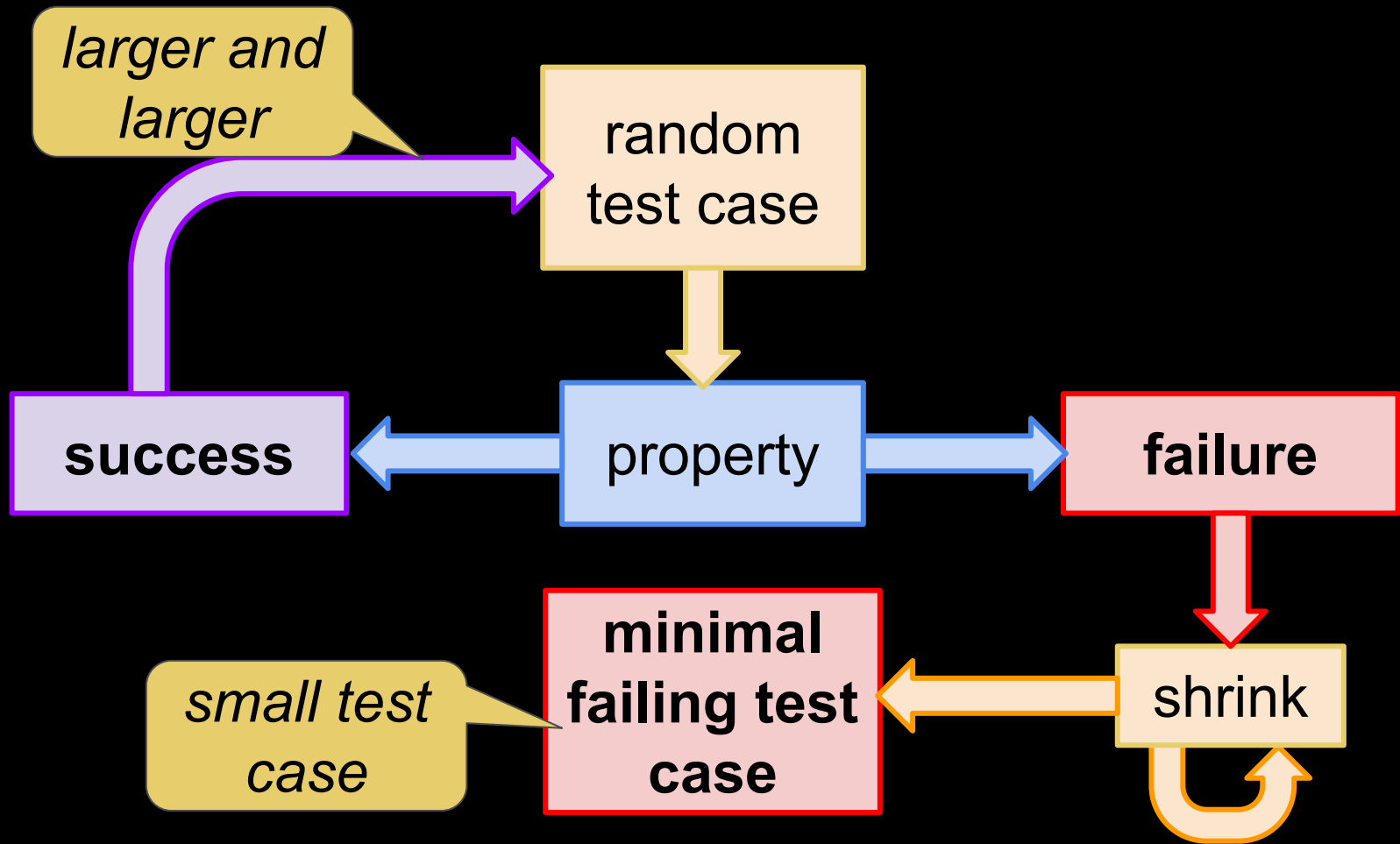
$a + b \rightarrow a, b$

$\text{if } e \text{ then } p \text{ else } q \rightarrow p, q$

$C[\text{var } x \text{ in } p] \rightarrow$   
 $\text{var } x \text{ in } C[p]$

$\text{while } e \text{ do } p \rightarrow$   
 $\text{if } e \text{ then } p \text{ else skip}$

*rules are applied  
repeatedly until a local  
minimum is found*



situation:

specification  
language

**A new language.**

programming  
language

You only have **one**  
interpreter/compiler.

how to test?

simple,  
efficient,  
complete

```
data Program
  = Skip
  | Var := Expr
  | Program :>>: Program
  | If Expr Program Program
  | While Expr Program
  | ...
```

```
compileAndRun :: Program -> State -> IO State
```

structural inductive  
testing of  
compileAndRun

```
prop_SequentialComposition ::  
    Program -> Program -> State -> IO Bool  
prop_SequentialComposition p q s1 =  
    do s3 <- compileAndRun (p :>>: q) s1  
        s2 <- compileAndRun p s1  
        s3' <- compileAndRun q s2  
    return (s3 == s3')
```

runs  
compiler/interpreter  
3 times

“self-consistency”

```
prop_While :: Expr -> Program -> State -> IO Bool
prop_While e p s1 =
  do s2 <- compileAndRun (While e p) s1
    s2' <- compileAndRun (If e (p :>>: While e p) Skip) s1
  return (s2 == s2')
```

runs  
compiler/interpreter  
2 times



```
prop_Skip :: State -> IO Bool
prop_Skip s1 =
  do s1' <- compileAndRun Skip s1
  return (s1 == s1')
```

- One property for each language construct
- Specification is now **complete**
  - but do not have to specify everything
  - **incremental specification**
- Compare to making new interpreter
  - these properties are as efficient as interpreter under test
  - they can **concentrate on logic**, not efficiency

step-wise inductive  
testing of  
compileAndRun

```
step :: Program -> State -> (Program, State)
```

```
prop_Step :: Program -> State -> IO Bool
```

```
prop_Step p s1 =
```

```
  do s2 <- compileAndRun p s1
```

```
    let (p', s1') = step p s1
```

```
    s2' <- compileAndRun p' s1'
```

```
    return (s2 == s2')
```

can also have one  
property for each  
step case

**example application 1:**  
Scoria -  
A language for IoT  
devices

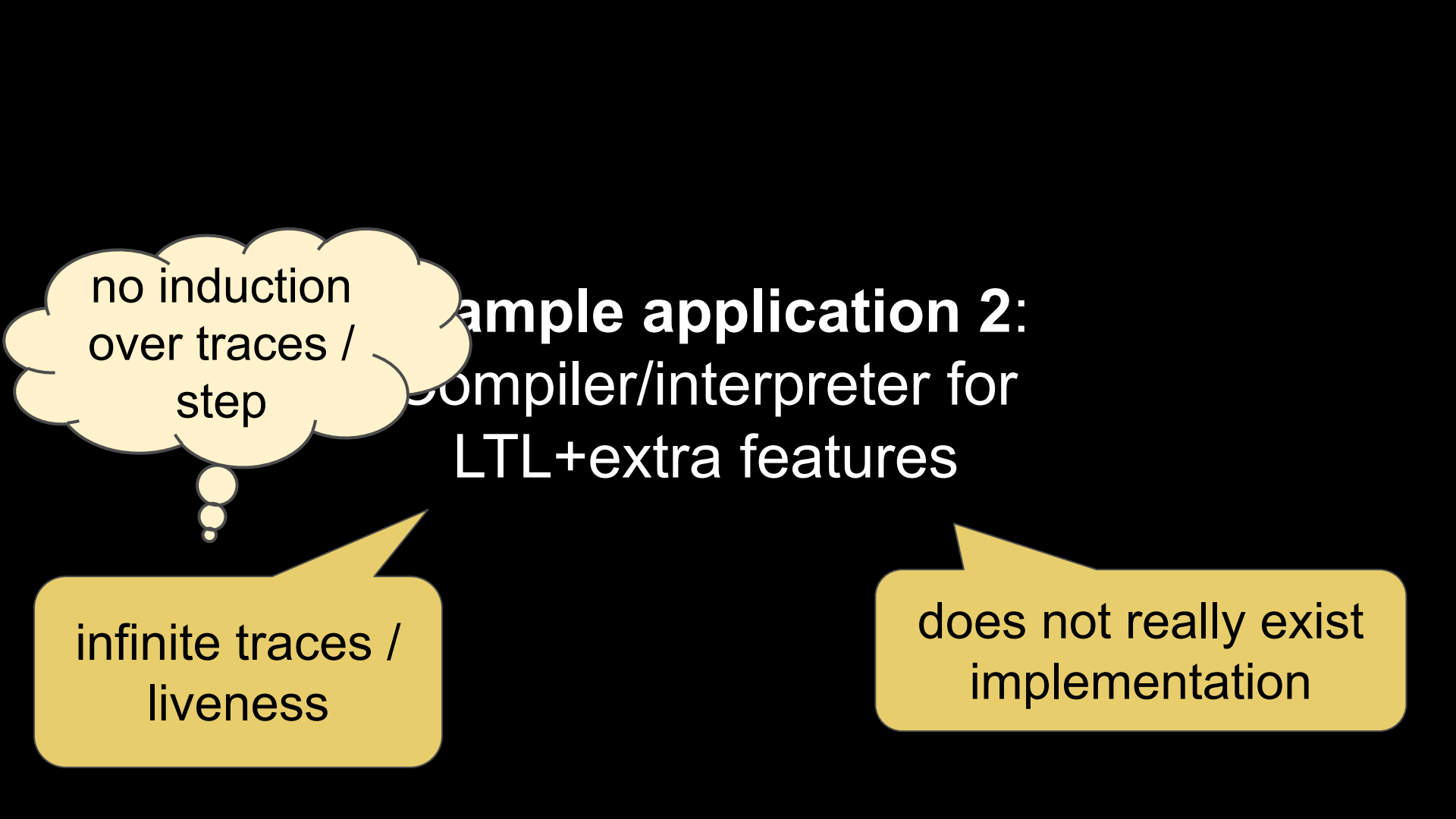
C compiler+runtime  
vs. interpreter

our own language +  
compiler

```
step :: Program -> State -> (Program, State)
```

```
prop_Function :: Program -> Program -> State -> IO Bool  
prop_Function f body p s1 =  
  do s2 <- compileAndRun (Def f body :>>: p) s1  
    s2' <- compileAndRun (Def f body :>>: inline f body p) s1  
  return (s2 == s2')
```

- We found bugs in the C-runtime
- We found bugs in our interpreter
  - invariants that did not hold
  - modelling optimizations we wanted to make in the compiler
- A few properties found almost all bugs (function inlining + sequential composition)



no induction  
over traces /  
step

## sample application 2: compiler/interpreter for LTL+extra features

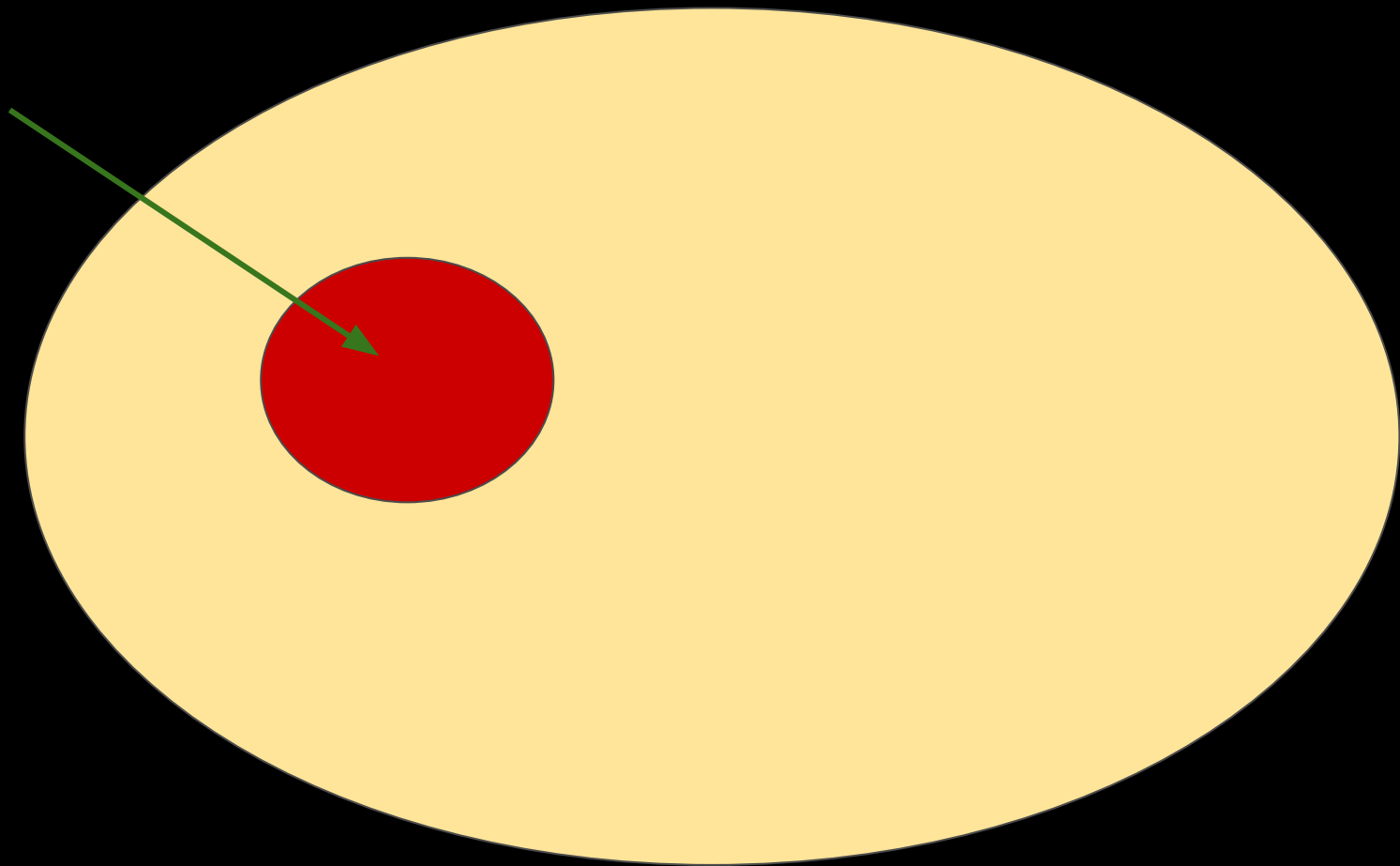
infinite traces /  
liveness

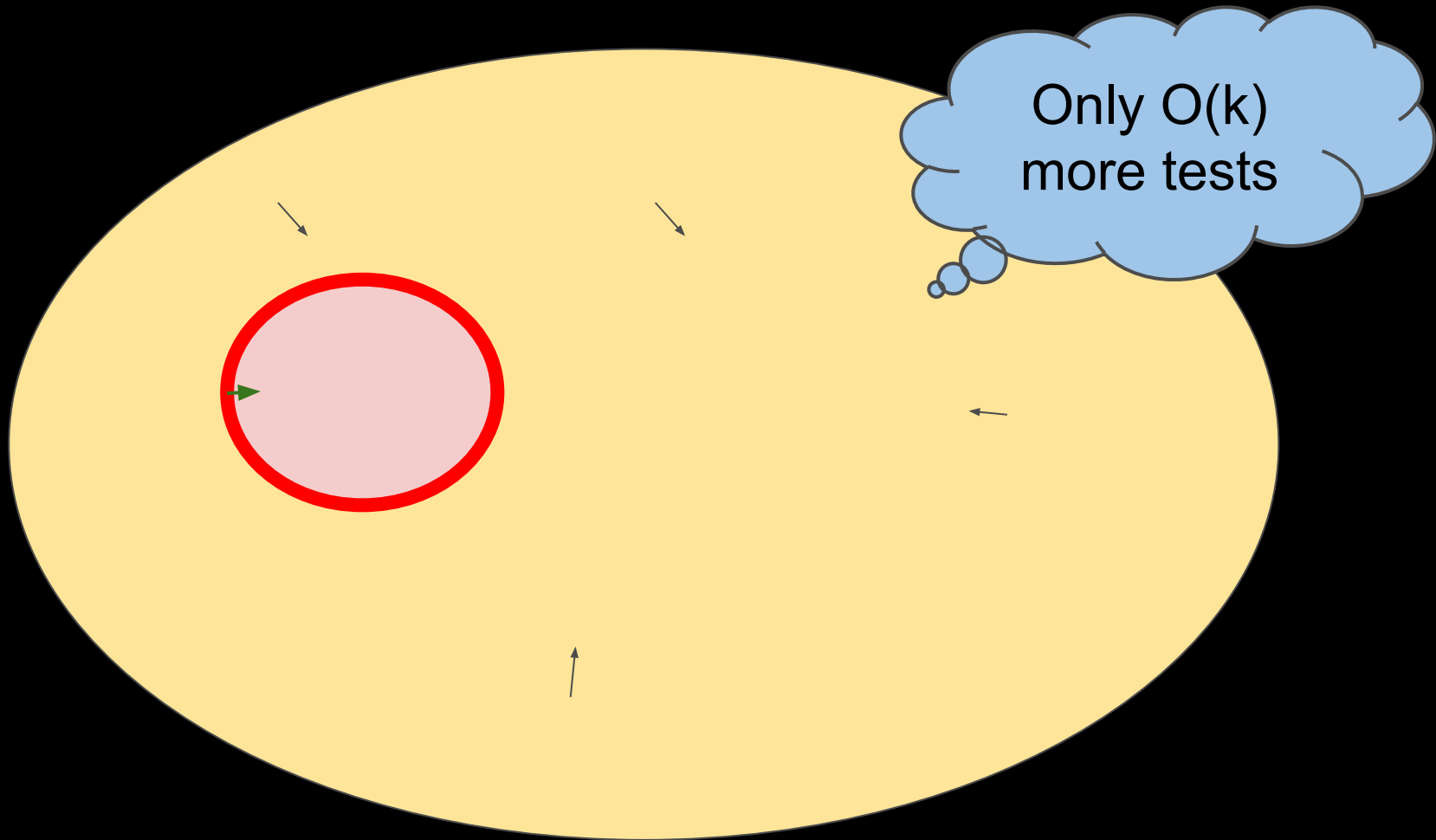
does not really exist  
implementation



```
prop_Box :: Form -> Trace -> Property
prop_Box p tr =
  do ok <- run (Box p) tr
    ok' <- forAllSteps tr (\tr' -> run p tr')
    return (ok == ok')
```

- Must fine-tune the trace generator to the property
- Flexible set-up during language design





# Summary

- It's useful to look at specifications as logical specifications and reformulate them into equivalent, but testable specifications
- simple, efficient, complete
- contrapositive testing, (co)inductive testing

Extra Slides

# Testing SAT-solvers

# Testing SAT-solvers

- If model and proof are generated
  - Direct soundness
  - Direct completeness
- If only model is generated when found
  - Direct soundness
  - Contrapositive testing for completeness
- If only yes/no answer
  - Inductive testing

# Testing Sorting



# Testing sorting functions

- Write down the simplest sorting function you can think of
  - *You trust this code*
- Show that the function you want to test has the same behavior
  - *How?*

# Testing FFT implementations

# Testing FFT

- Using exact arithmetic
  - Implementation is still fast
  - Specification is extremely slow
- Base cases
  - vectors  $[0, \dots, 0, 1, 0, \dots, 0]$
- Step cases
  - $a * \text{fft } v = \text{fft } (a * v)$
  - $\text{fft } v + \text{fft } w \equiv \text{fft } (v + w)$