Reasoning about Consensus Protocols

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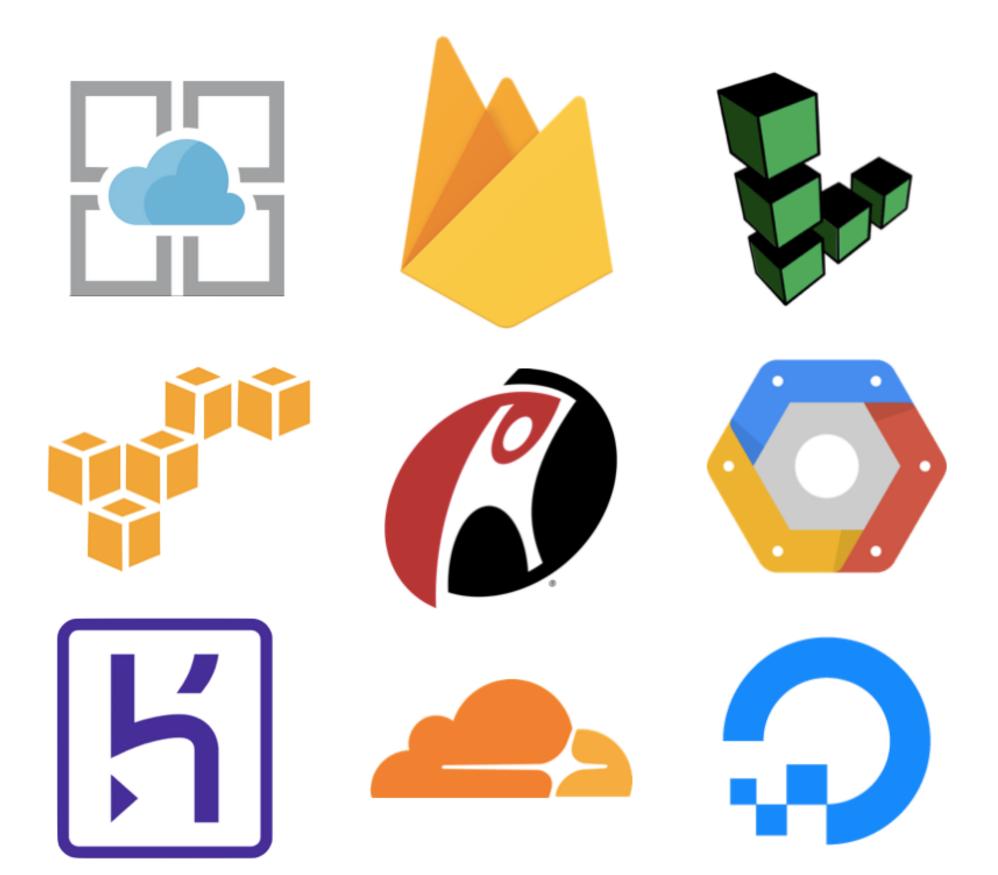
Ilya Sergey



Consensus

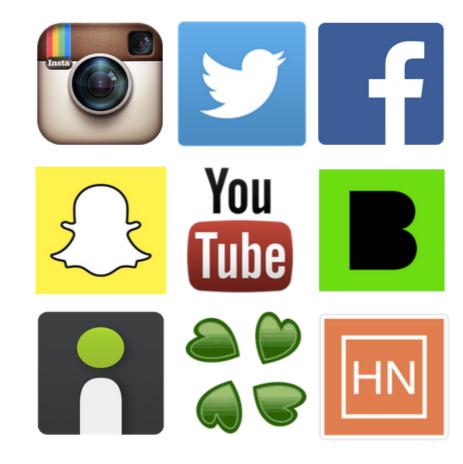
- Common meaning: a way for a set of parties to come to a shared agreement.
- In computing: ensuring that among the values proposed by a collection of processes, a *single one* is chosen.
 - Uniformity: Only a *single* value is chosen
 - Non-triviality: Only a value that has been proposed may be chosen
 - Irrevocability: Once agreed on a value, the processes do not change their decision.

Why Consensus?













ethereum

Why Consensus at SIGPL School?

- Because distributed systems are correctness-critical software.
- Reasoning about correctness of distributed consensus and its applications is a *difficult problem*.

• PL area provides verification methods and language abstractions.

Why Distributed Consensus is difficult?

- Arbitrary message delays (asynchronous network)
- Network partitions
- Message reorderings
- Malicious (Byzantine) parties

Independent parties (nodes) can go offline (and also back online)

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Reaching a Consensus

(and constructing a protocol for this)



Reaching a Consensus on where to have a dinner

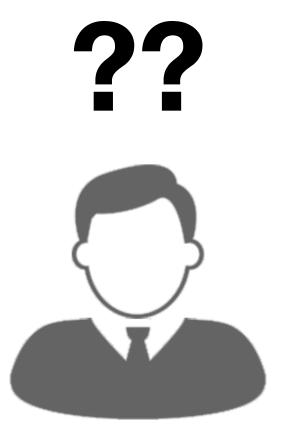






Parkview

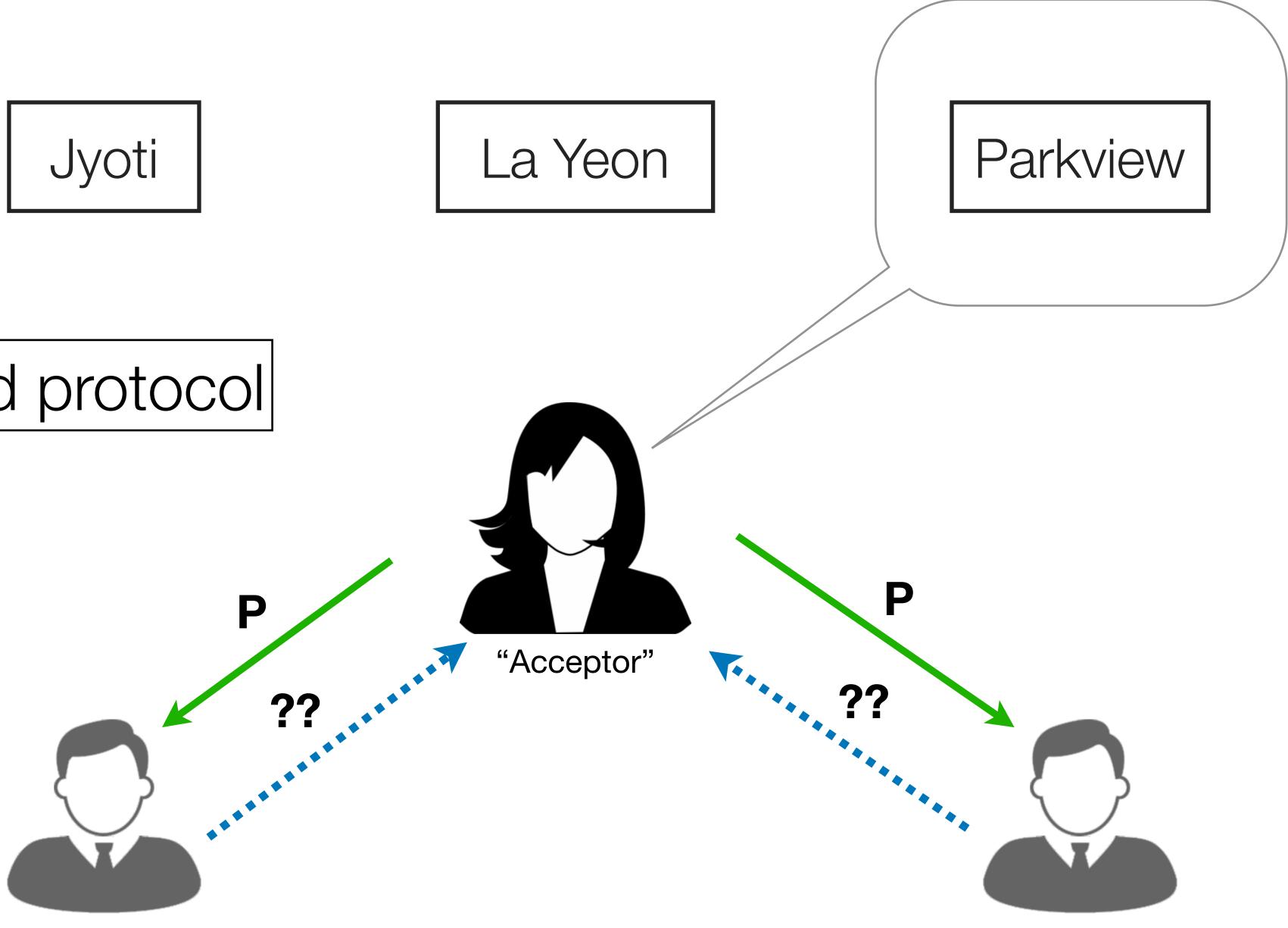








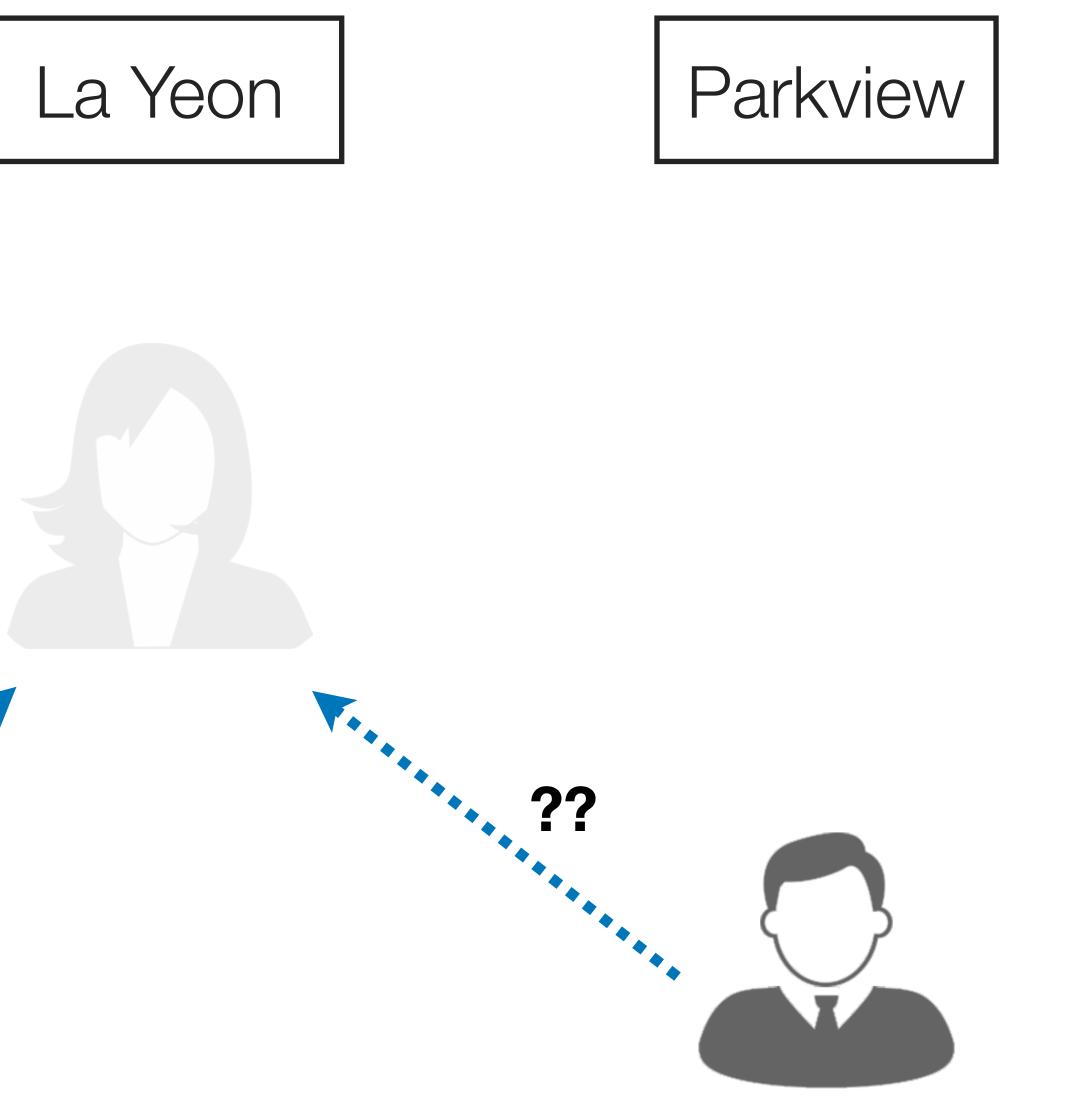


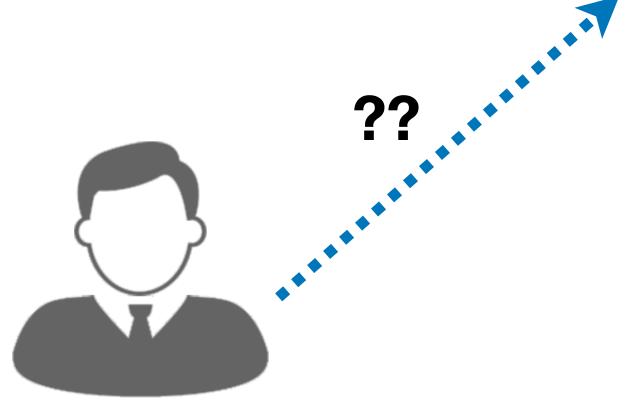


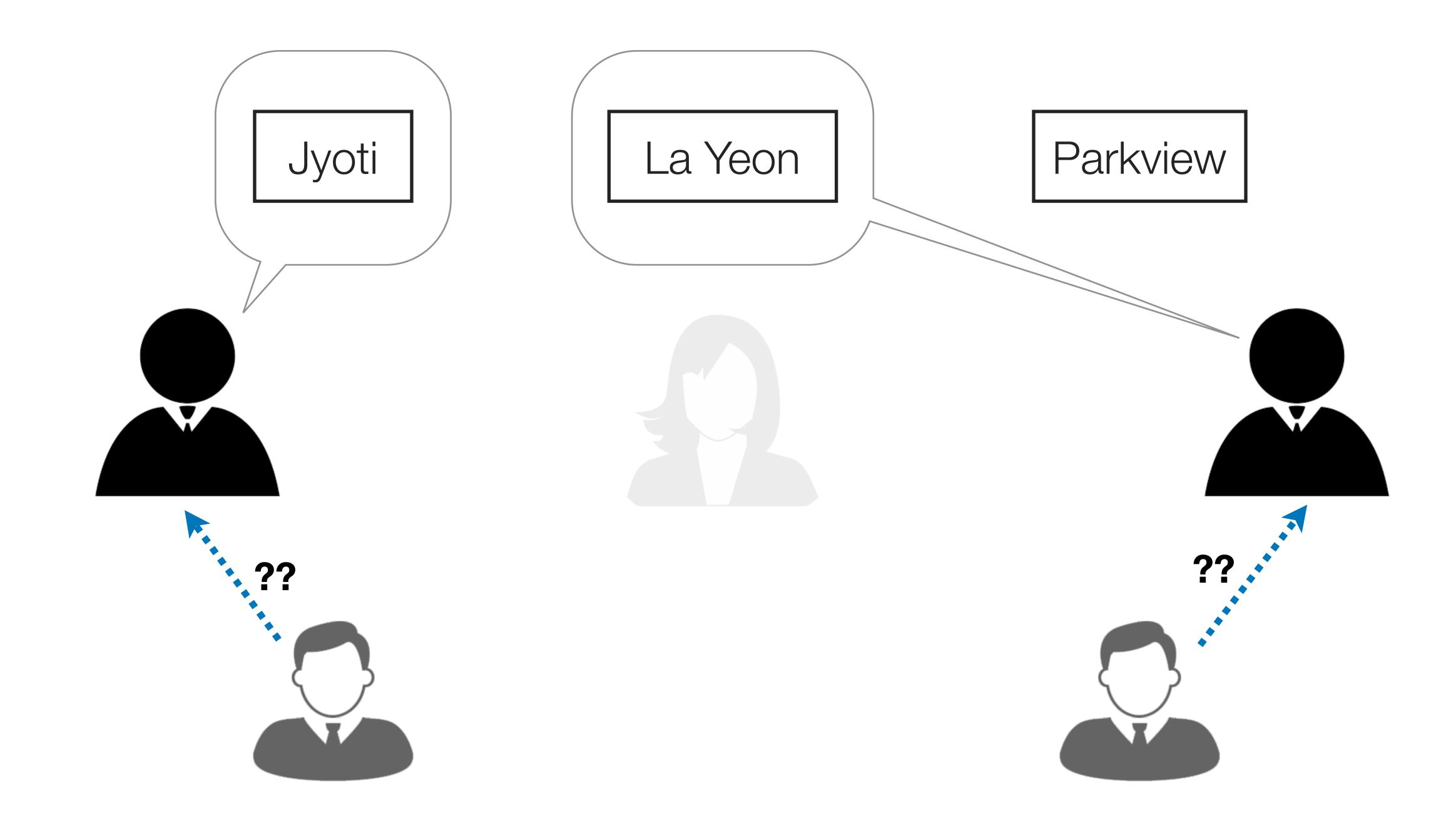
Problem 1

A single acceptor can go offline or take forever to answer.









Problem 2

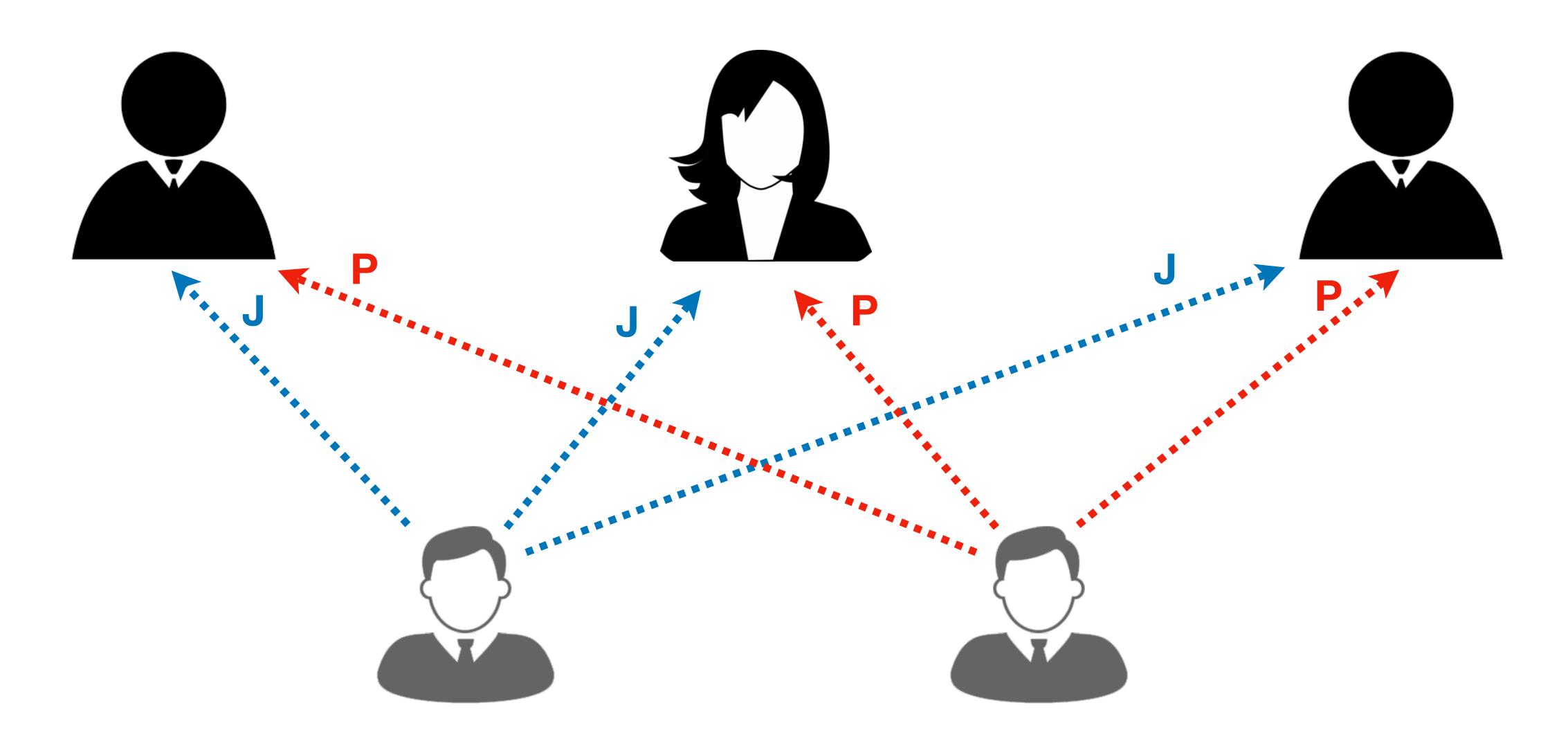
Multiple acceptors might disagree on the outcomes: now they need to reach a consensus themselves.

- **Proposers**: suggest a value (a restaurant to go);
- Acceptors: support some proposal;
- The proposer with a *majority of acceptors* supporting its proposal wins.

Separation of Concerns

Others learn the outcome by querying all the acceptors.

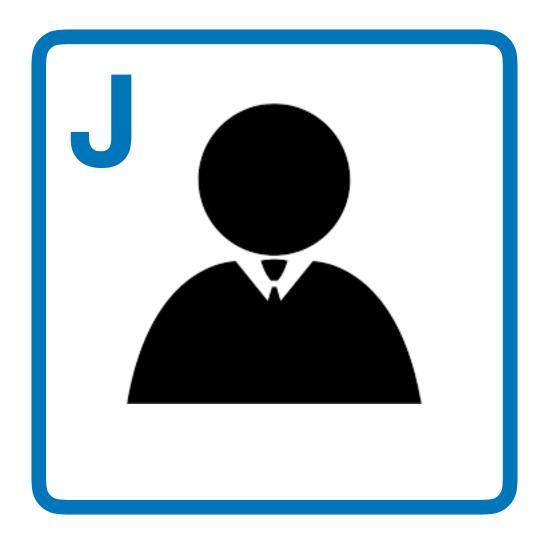


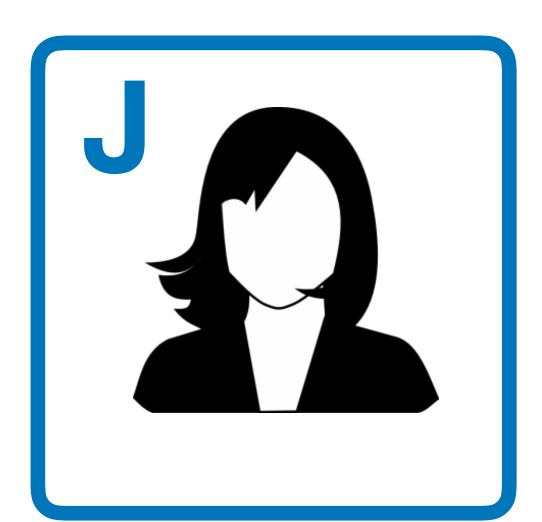


Acceptors

Proposers

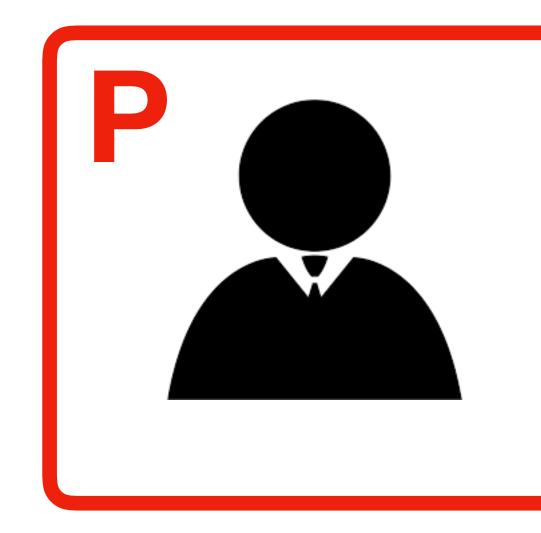








Acceptors









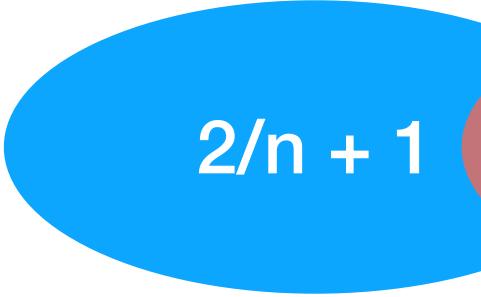
- Common meaning: Quorum is the minimum number of members to conduct the business on behalf of the entire group they represent;
- In computing: quorum is a necessary number of processes to agree on the decision in the presence of potentially faulty ones.

Key Idea 1

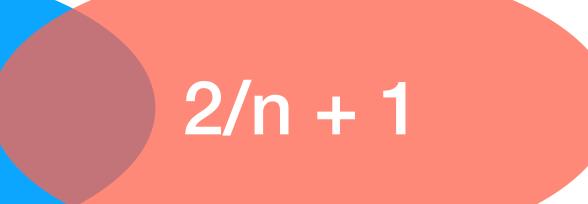
Rely on majority quorums for agreement to prevent the "split brain" problem.

Key Properties of Quorums

Property 1: any two quorums must have non-empty intersection



• Property 2: no need for the global agreement: can tolerate some faults



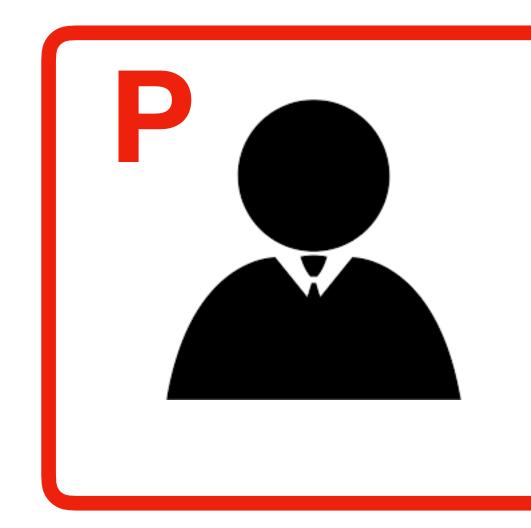


Quorum of n/2 + 1 acceptors



n = 3







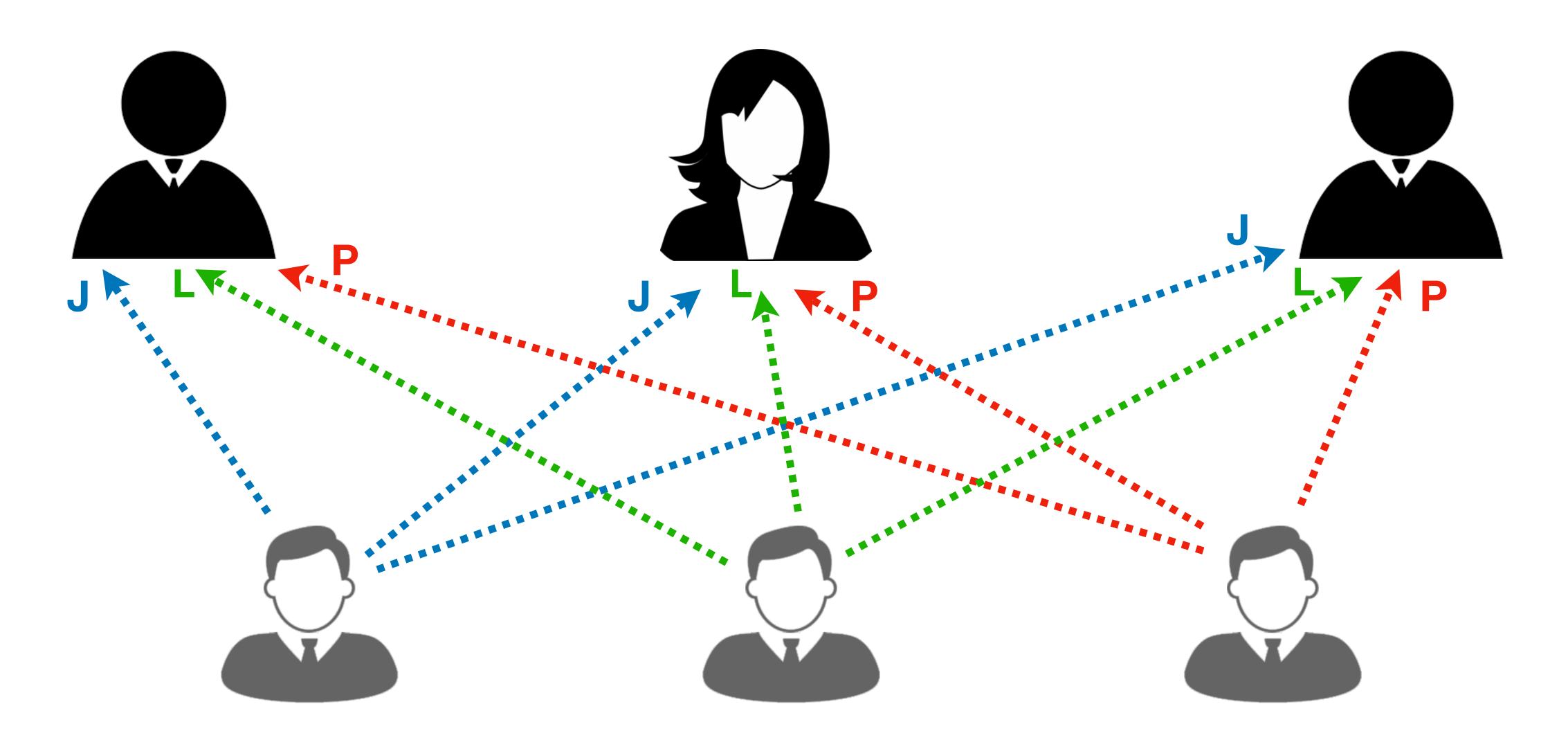


Problem

A quorum is difficult to obtain in a single interaction.

As the result, such a system will often get stuck.

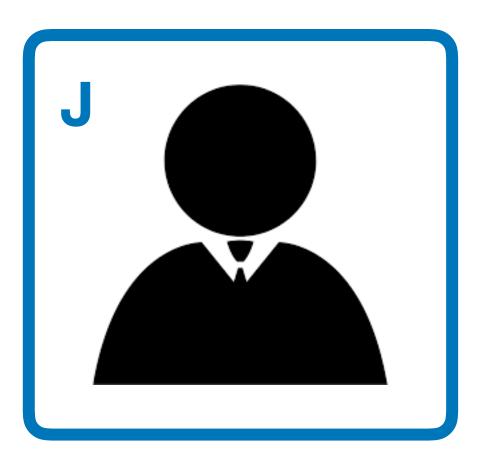




Acceptors

Proposers









Acceptors







Proposers

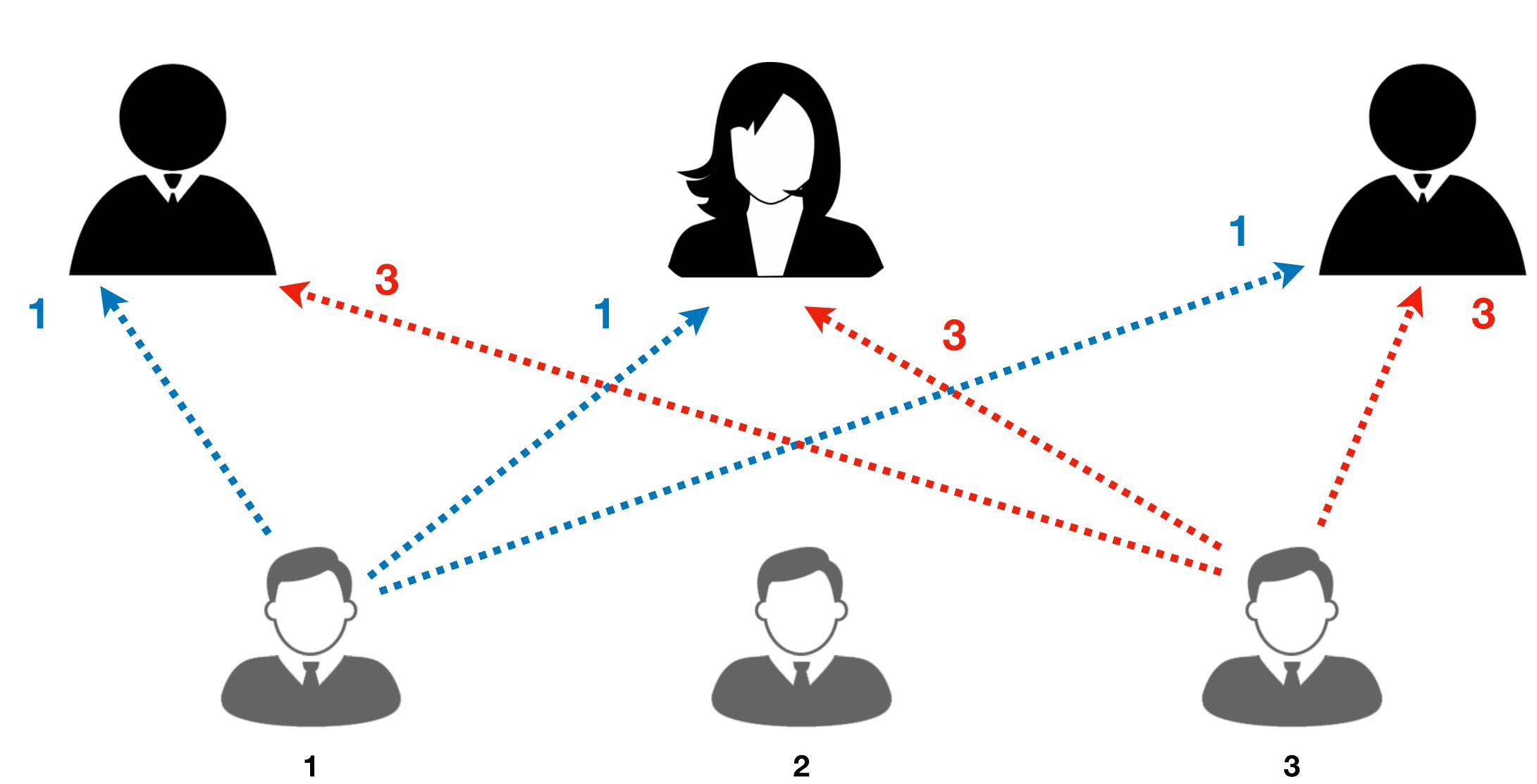
Key Ideas 2 and 3

- Proceed in rounds:
 - A proposer first "secures" itself a quorum, willing to support its proposal (i.e., becomes a "leader");
 - Only if a quorum is secured, it goes on to "propose" a value.
- Introduce fixed globally known priorities between proposers to "break ties" when securing quorums.
 - Acceptors only "choose to support" proposers with higher priorities than they have already seen.

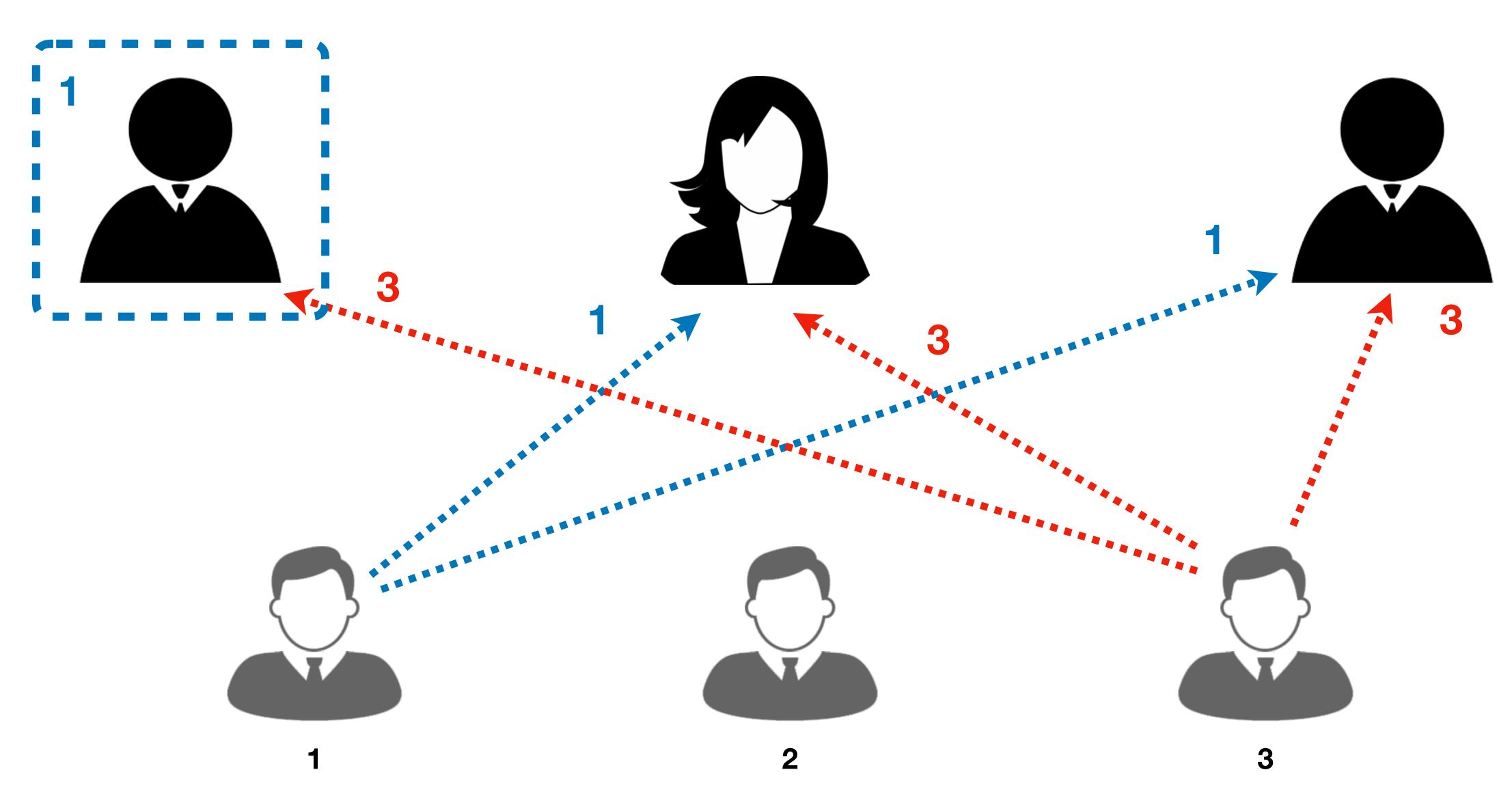
Some Terminology

- Rounds **Phases**
 - Phase 1 "prepare", securing quorums to propose
 - Phase 2 "accept", sending values to accept
- Fixed priorities **Ballots**

curing quorums to propose ding values to accept



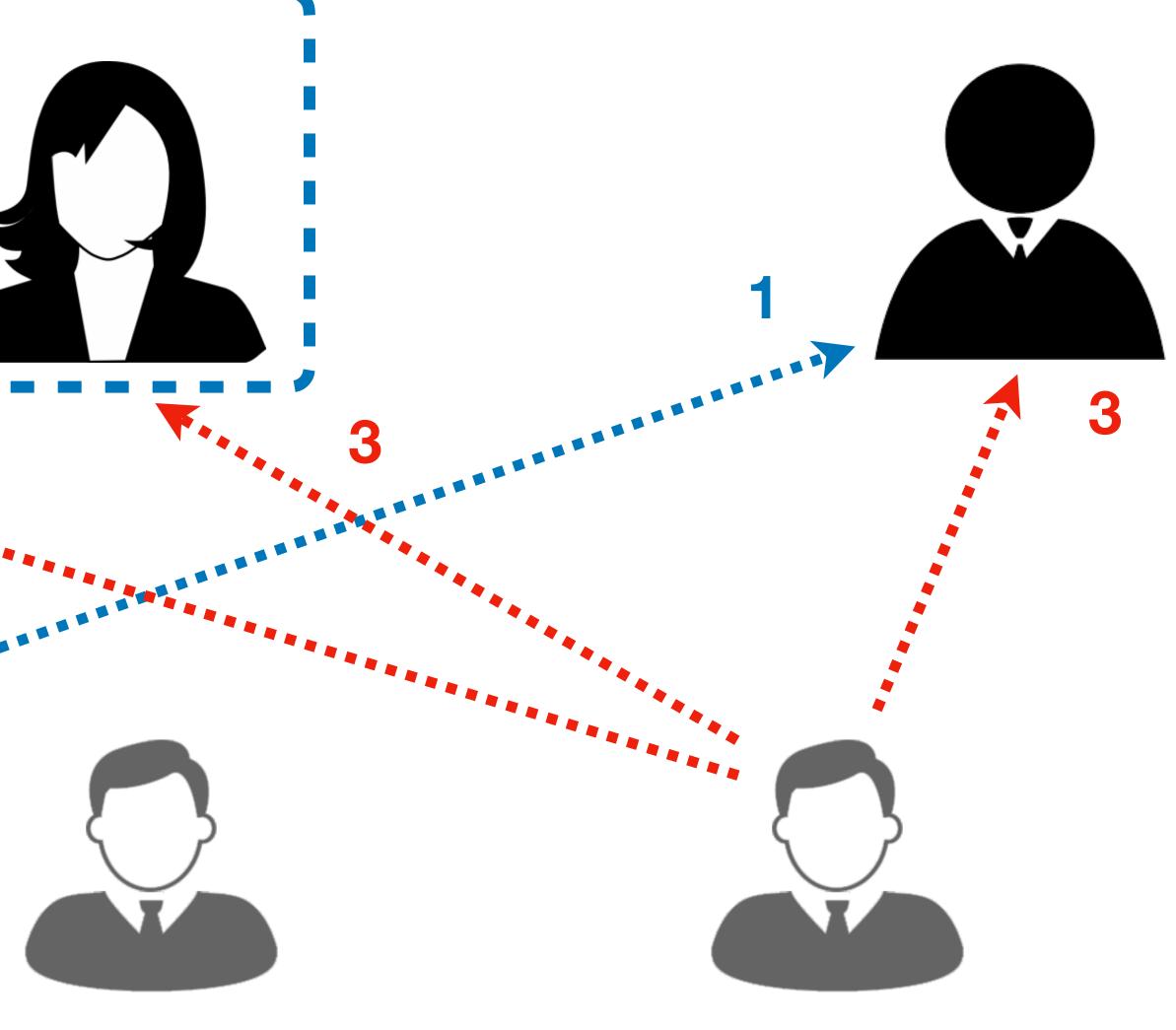
Phase 1



Phase 1

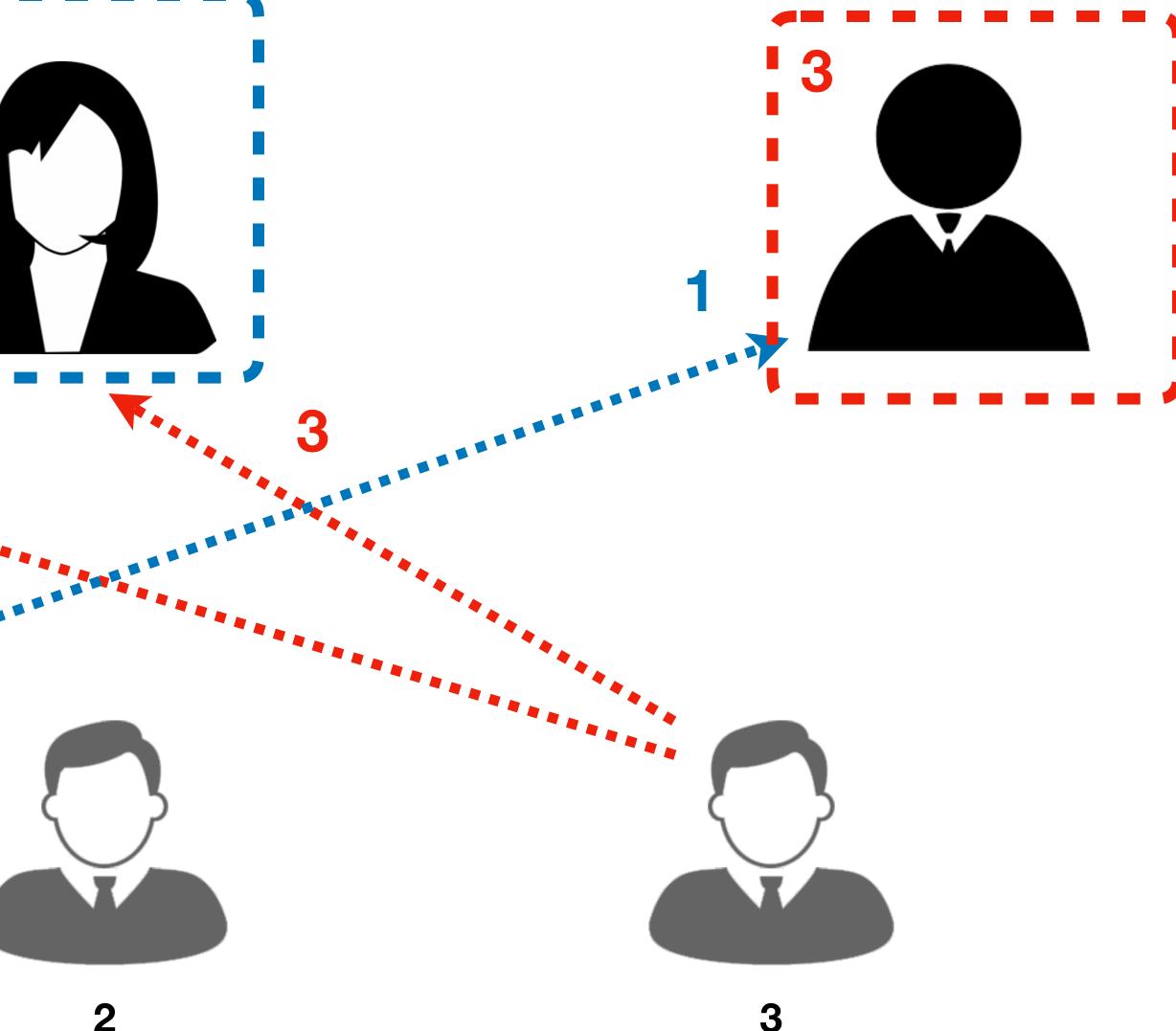
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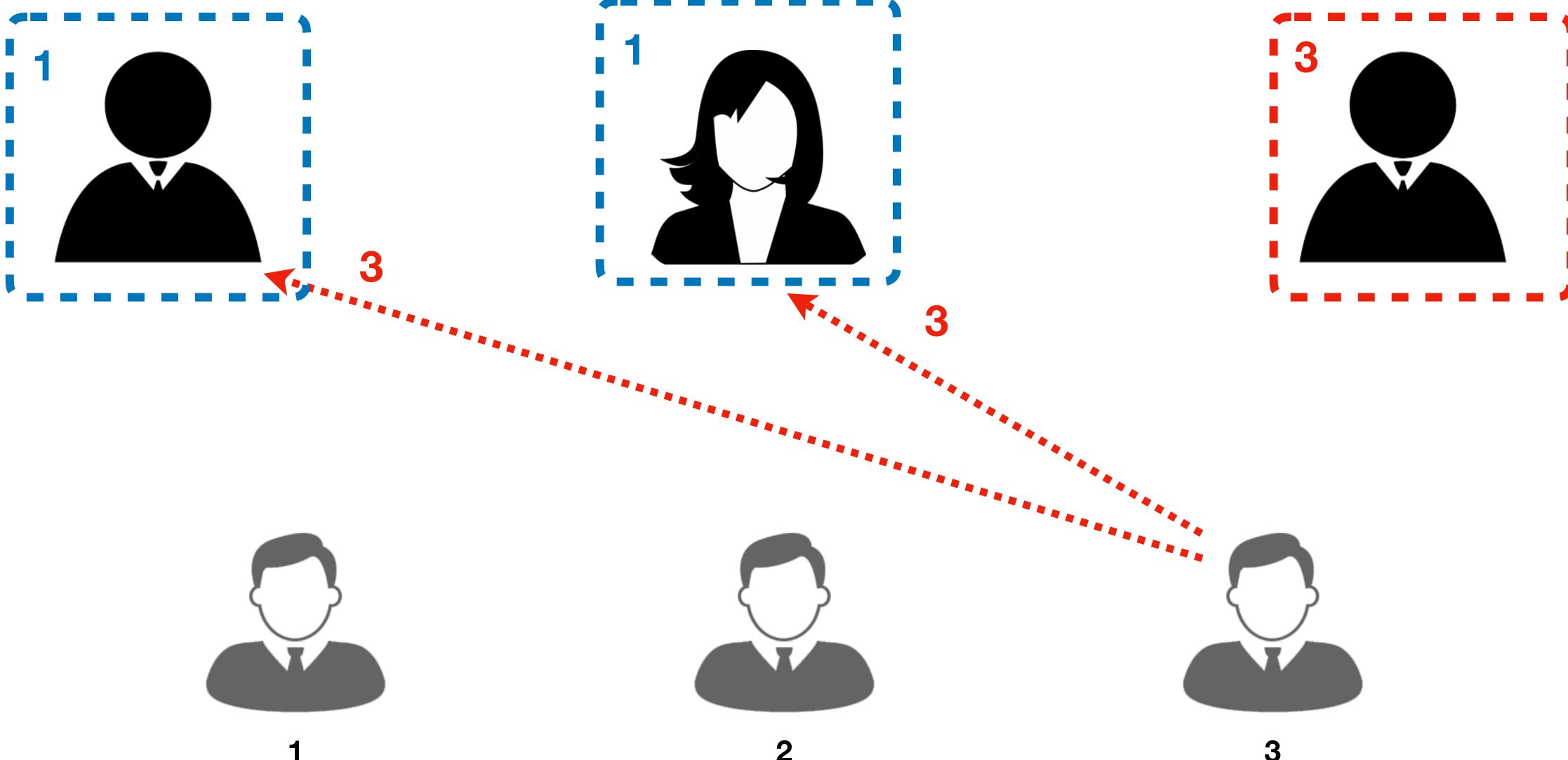


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Phase 1



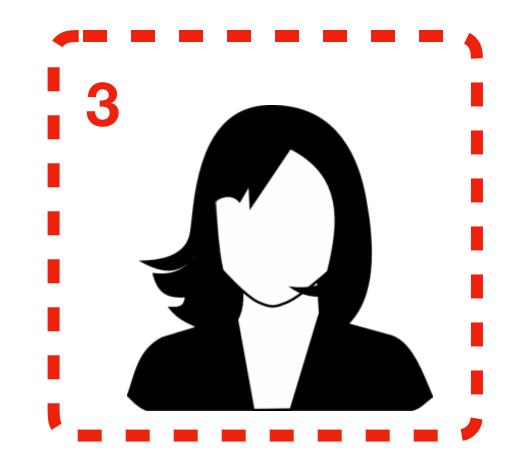






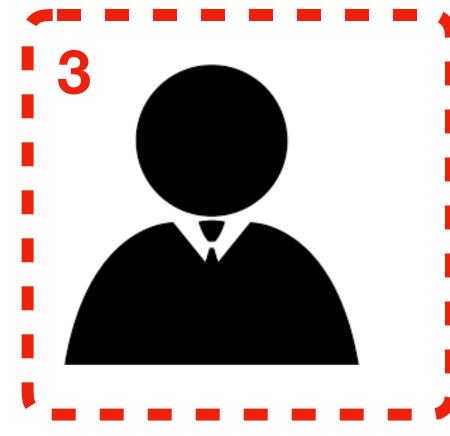
Phase 1







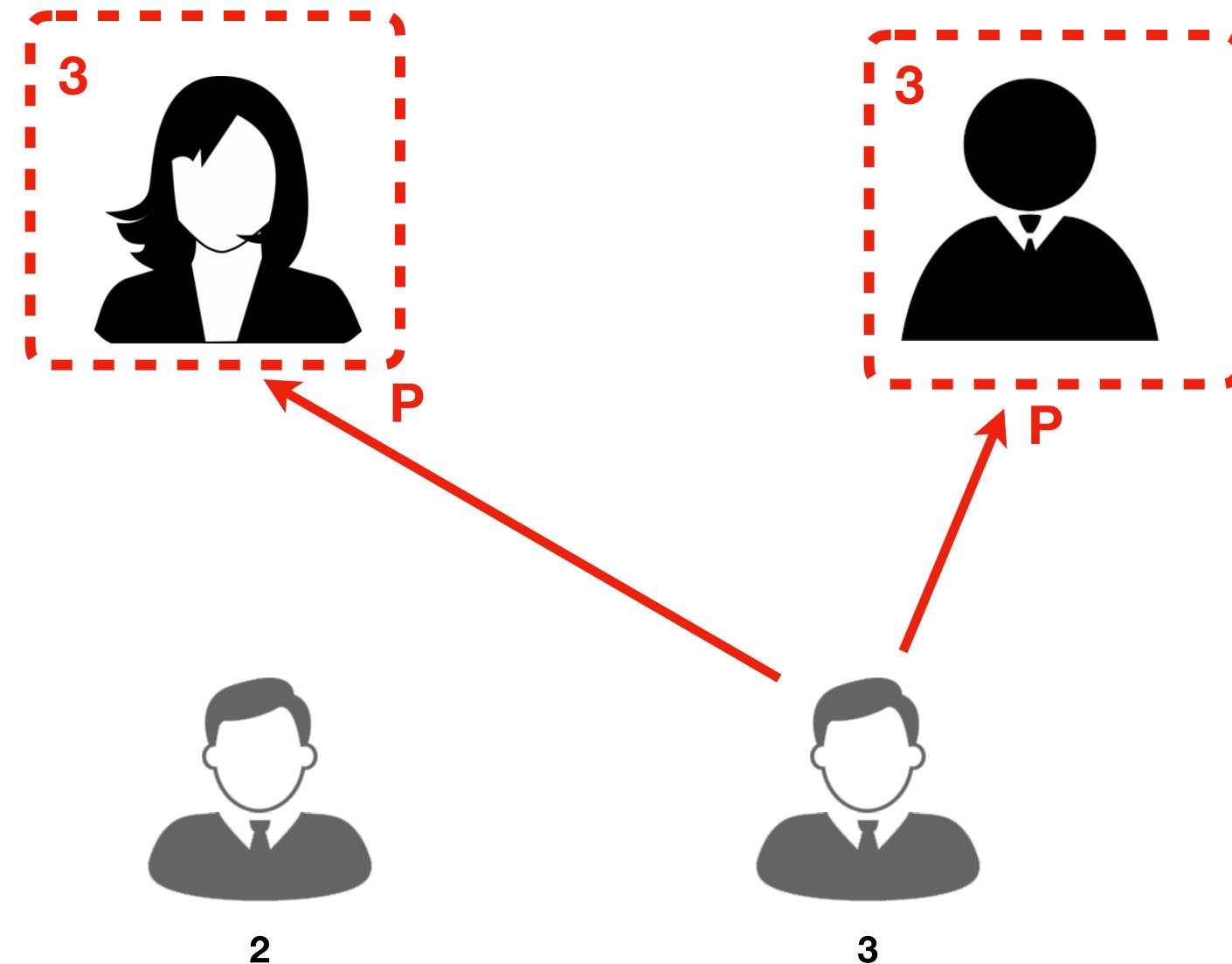
Phase 1













1

Phase 2

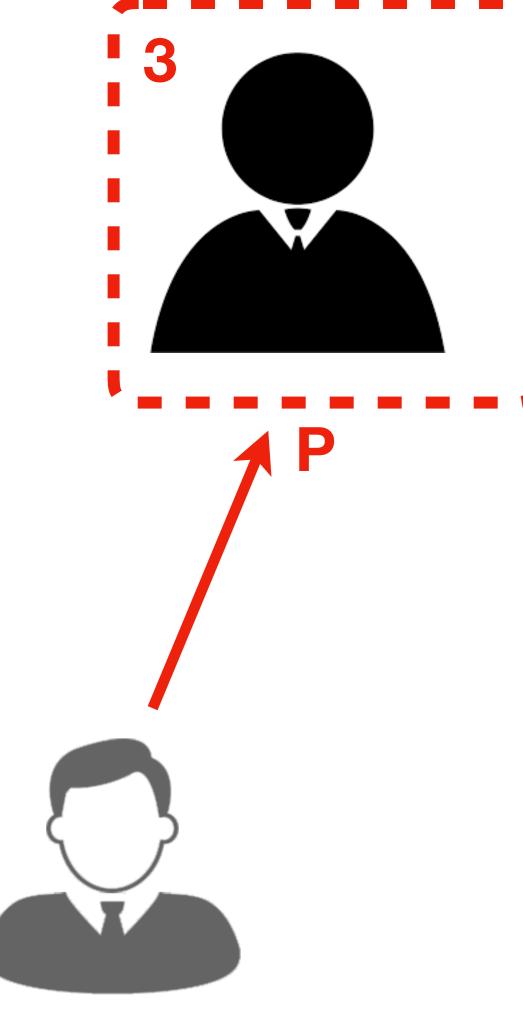






Phase 2



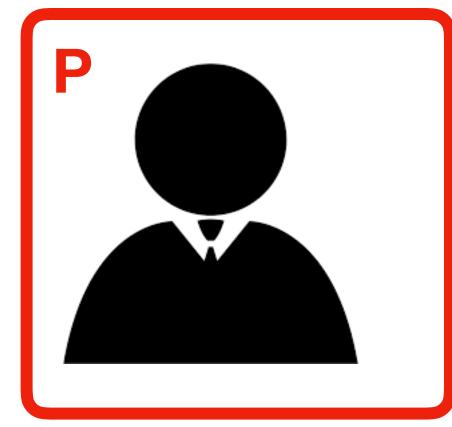








Phase 2



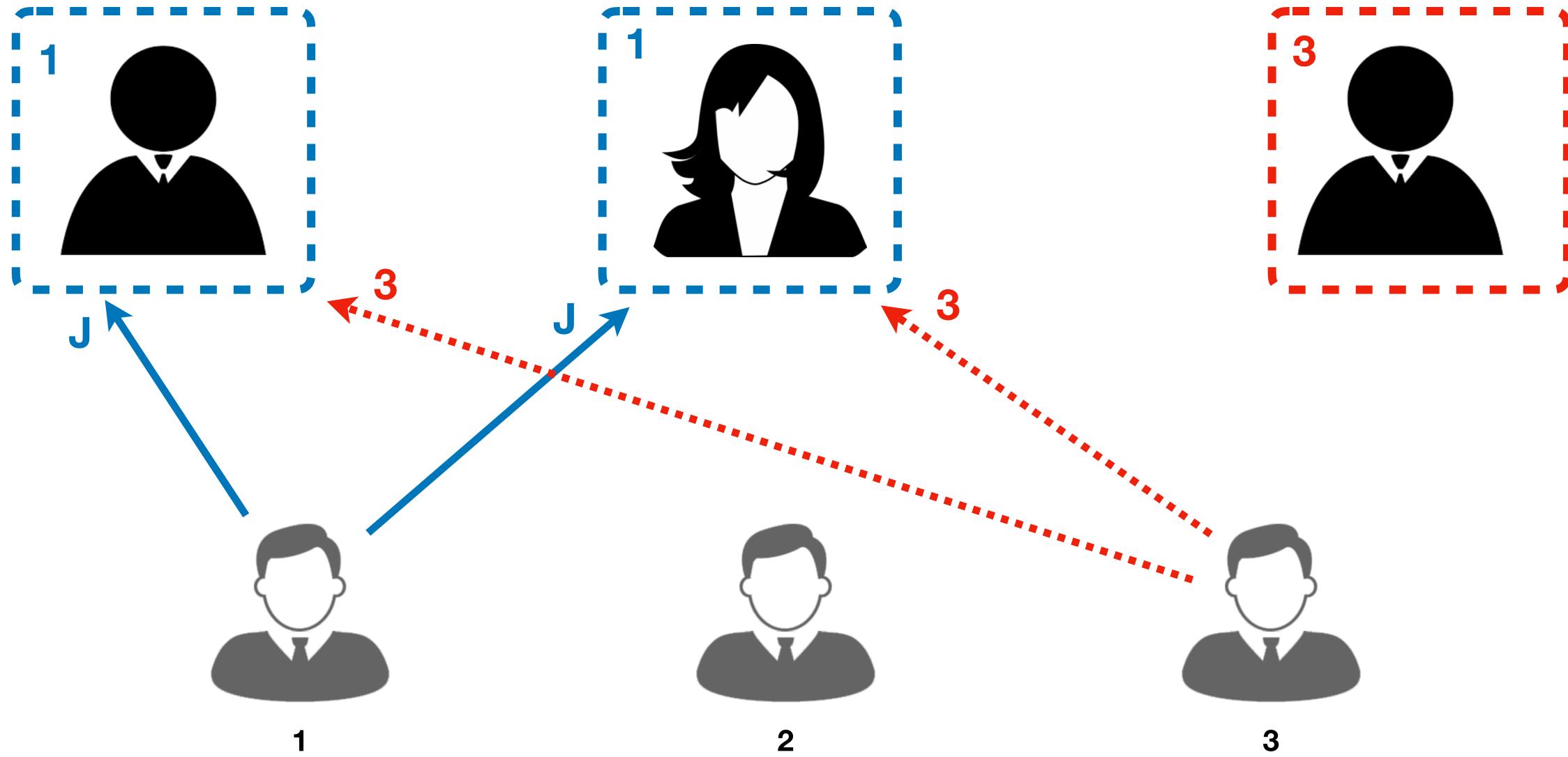




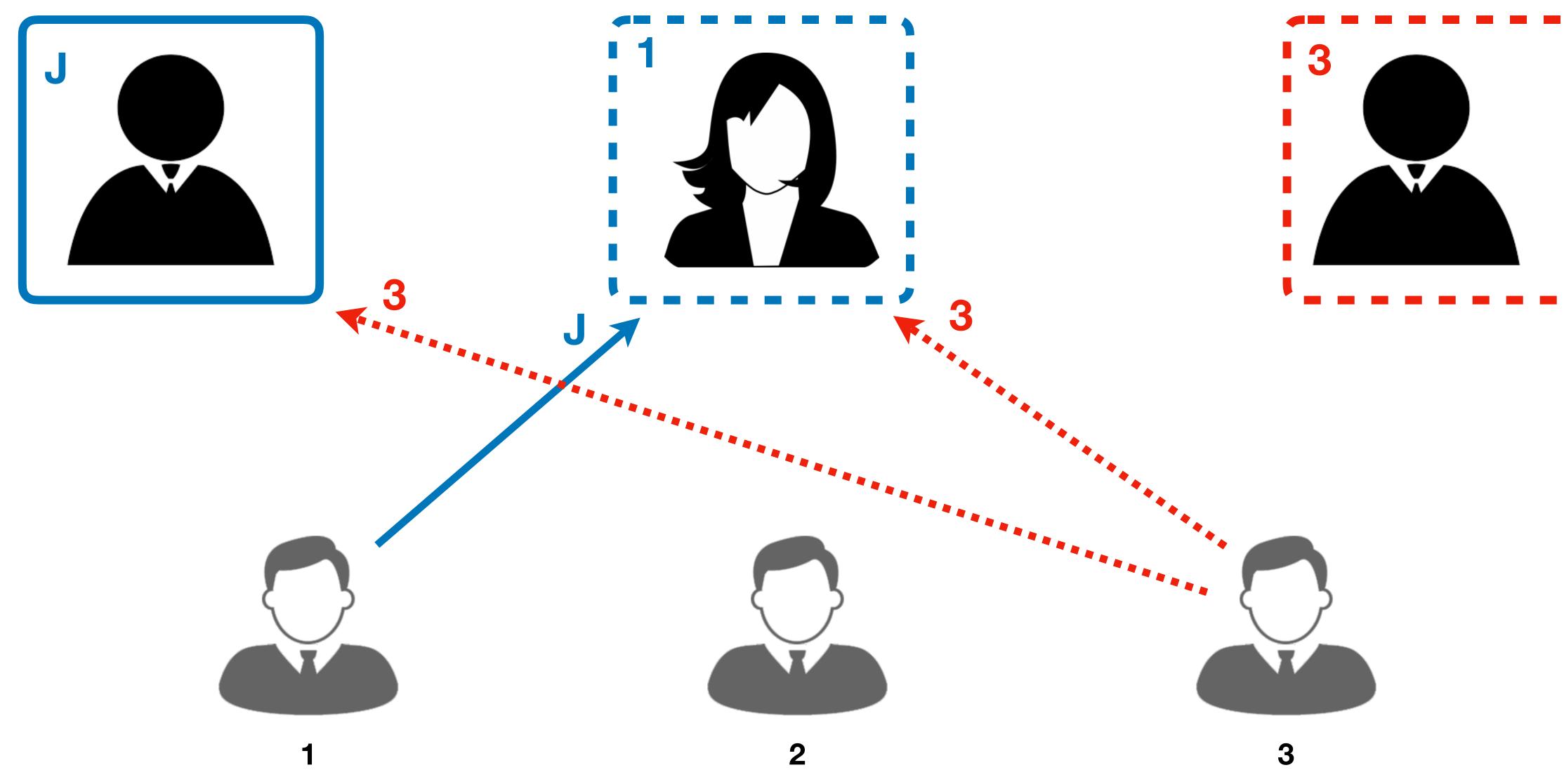
Problem 3

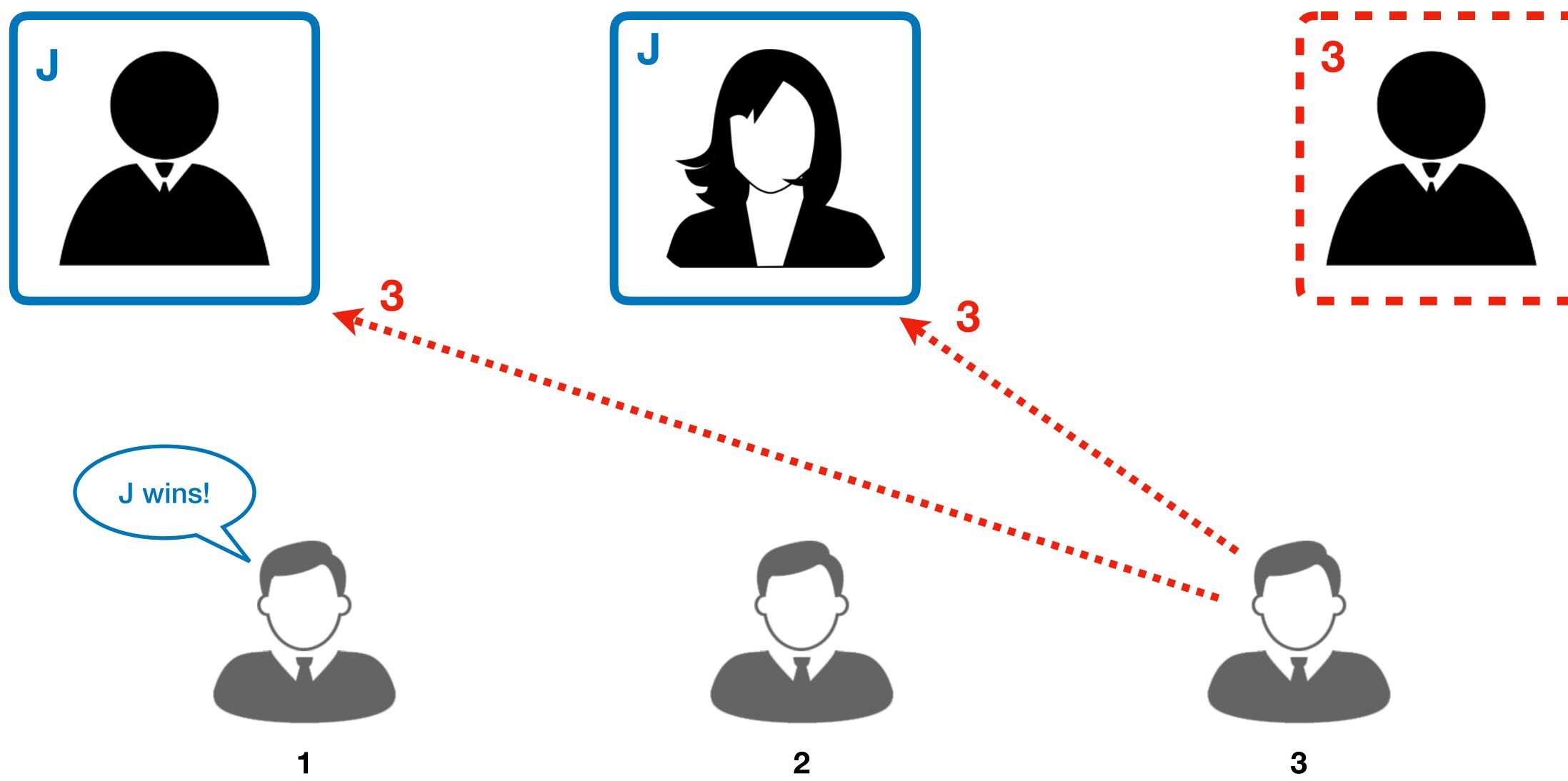
Because of asynchrony, low-priority Phase 2 can be interrupted by a high-priority Phase 1

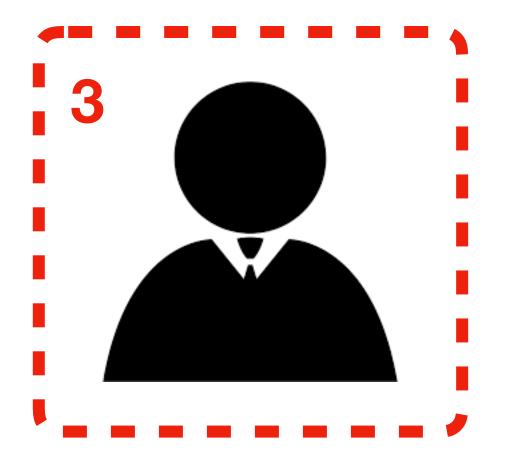
Phase 2

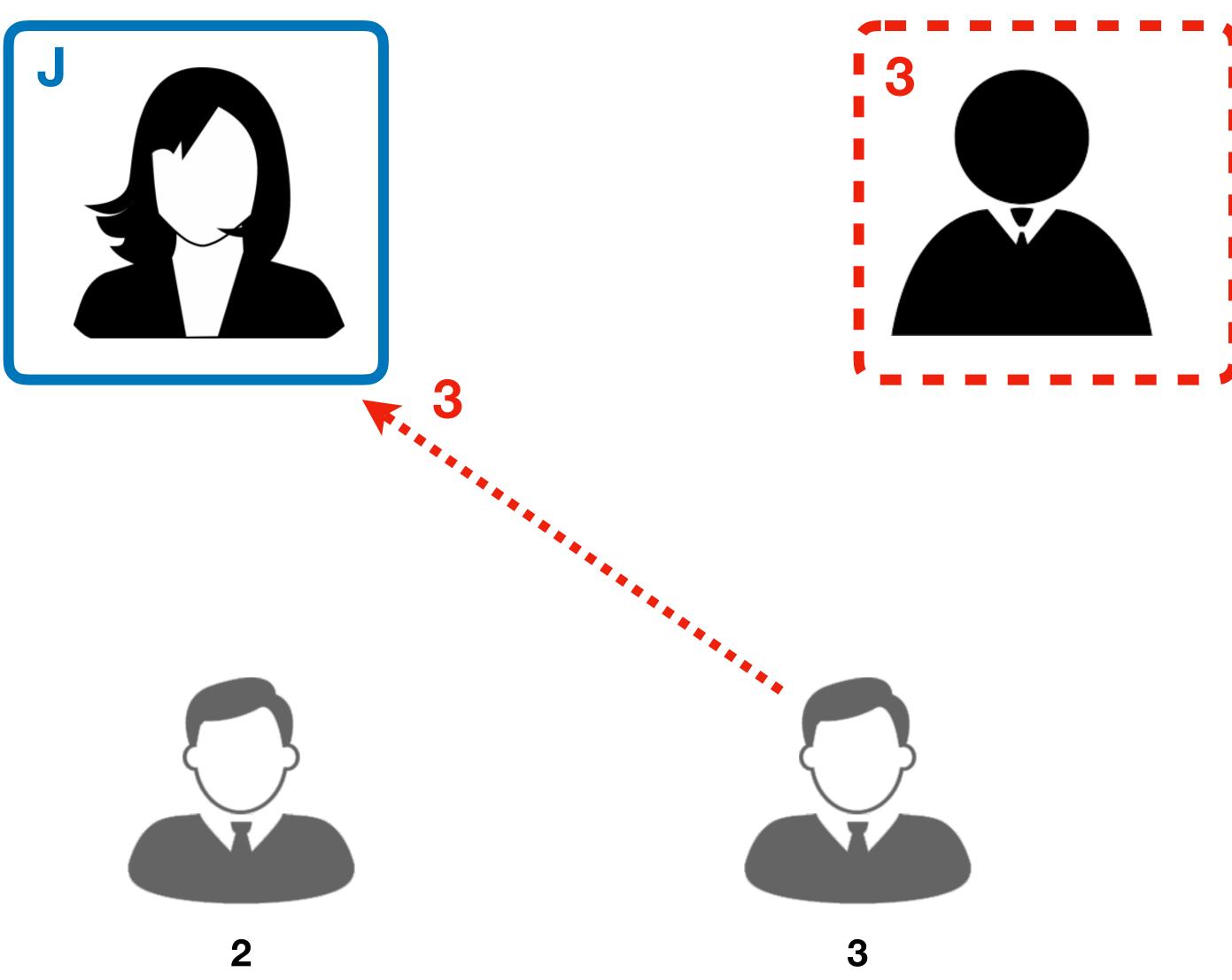


Phase 1

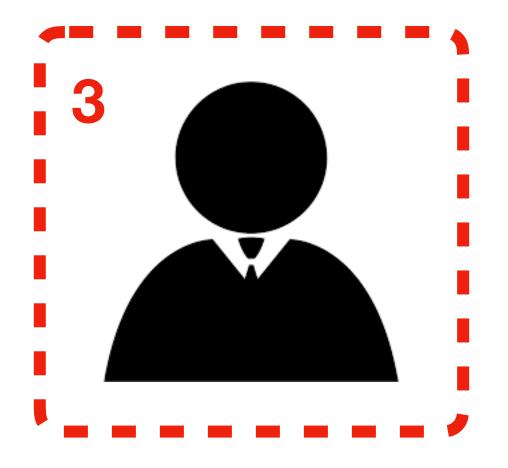


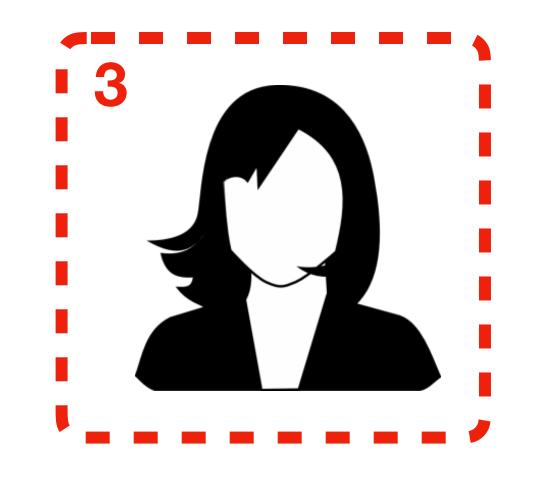






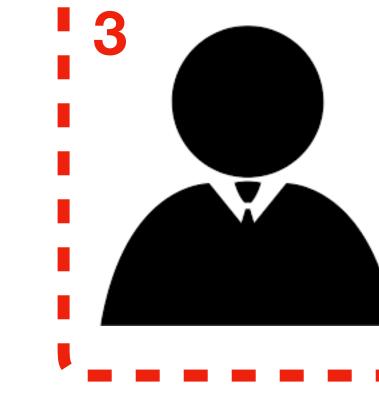






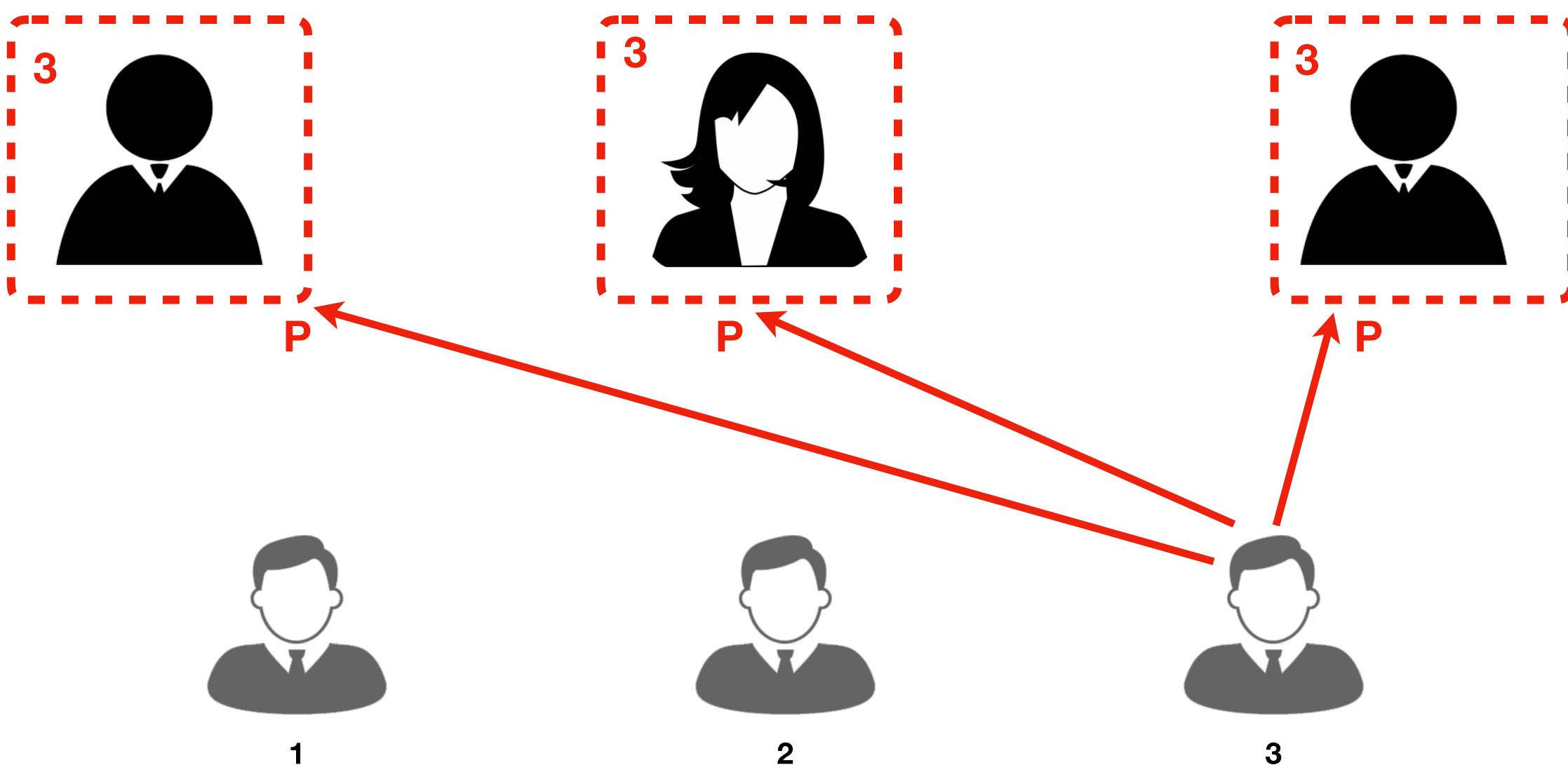




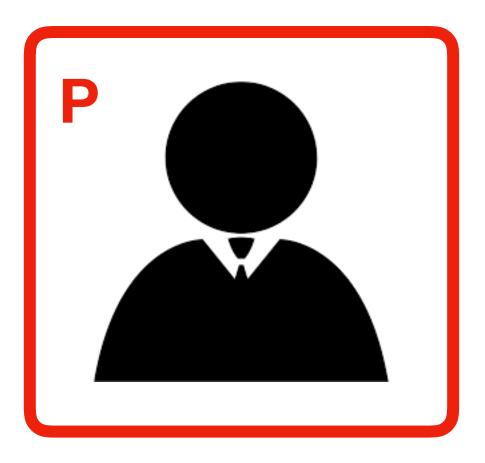




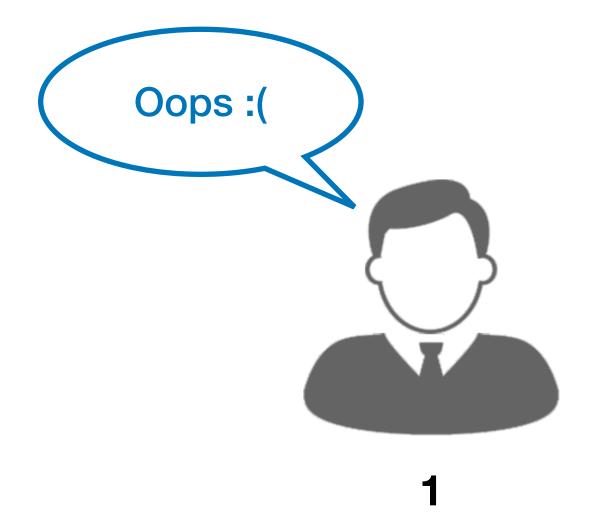


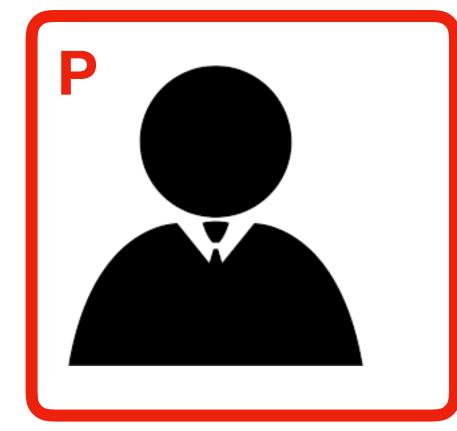
















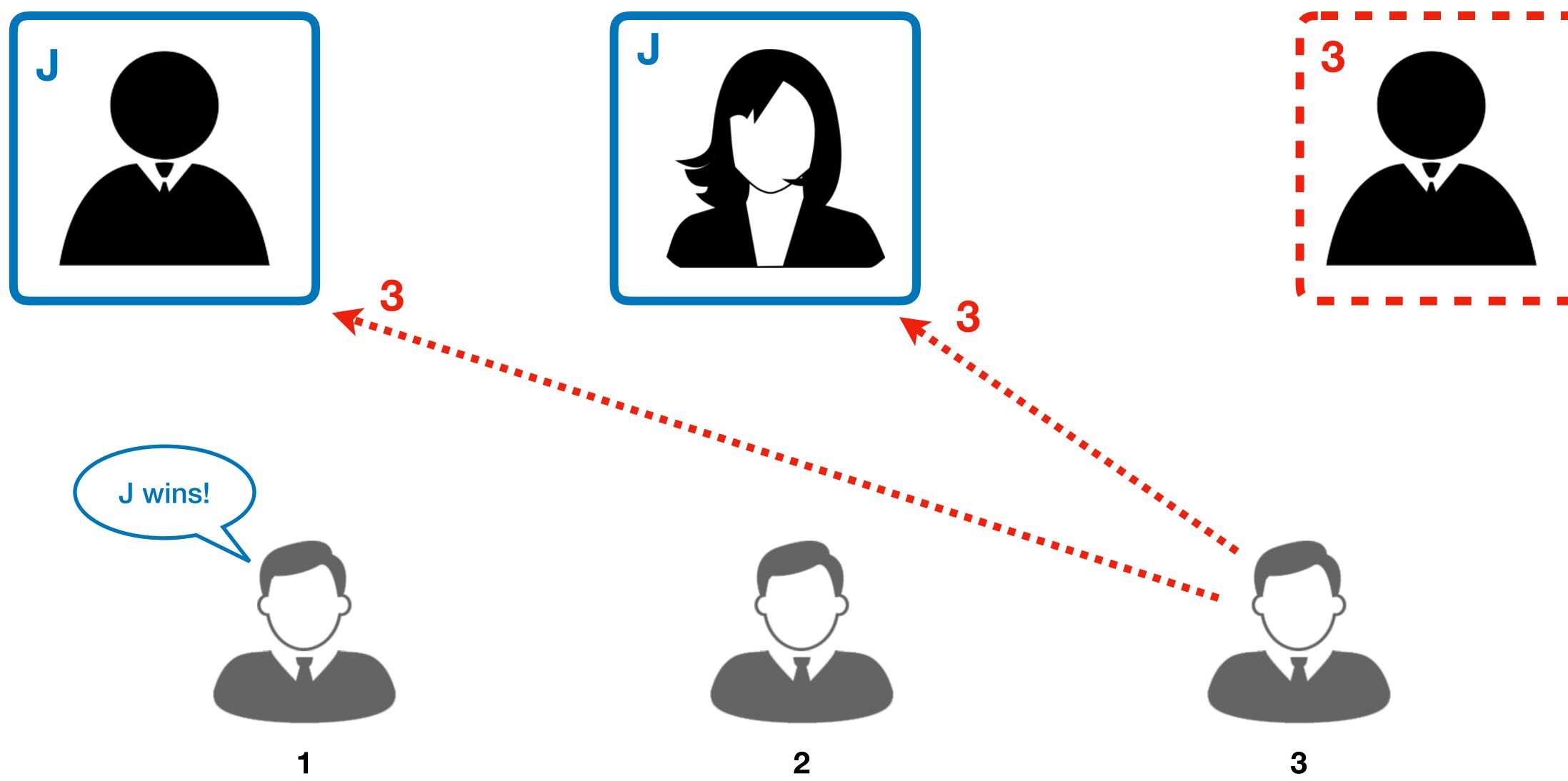
Problem 3

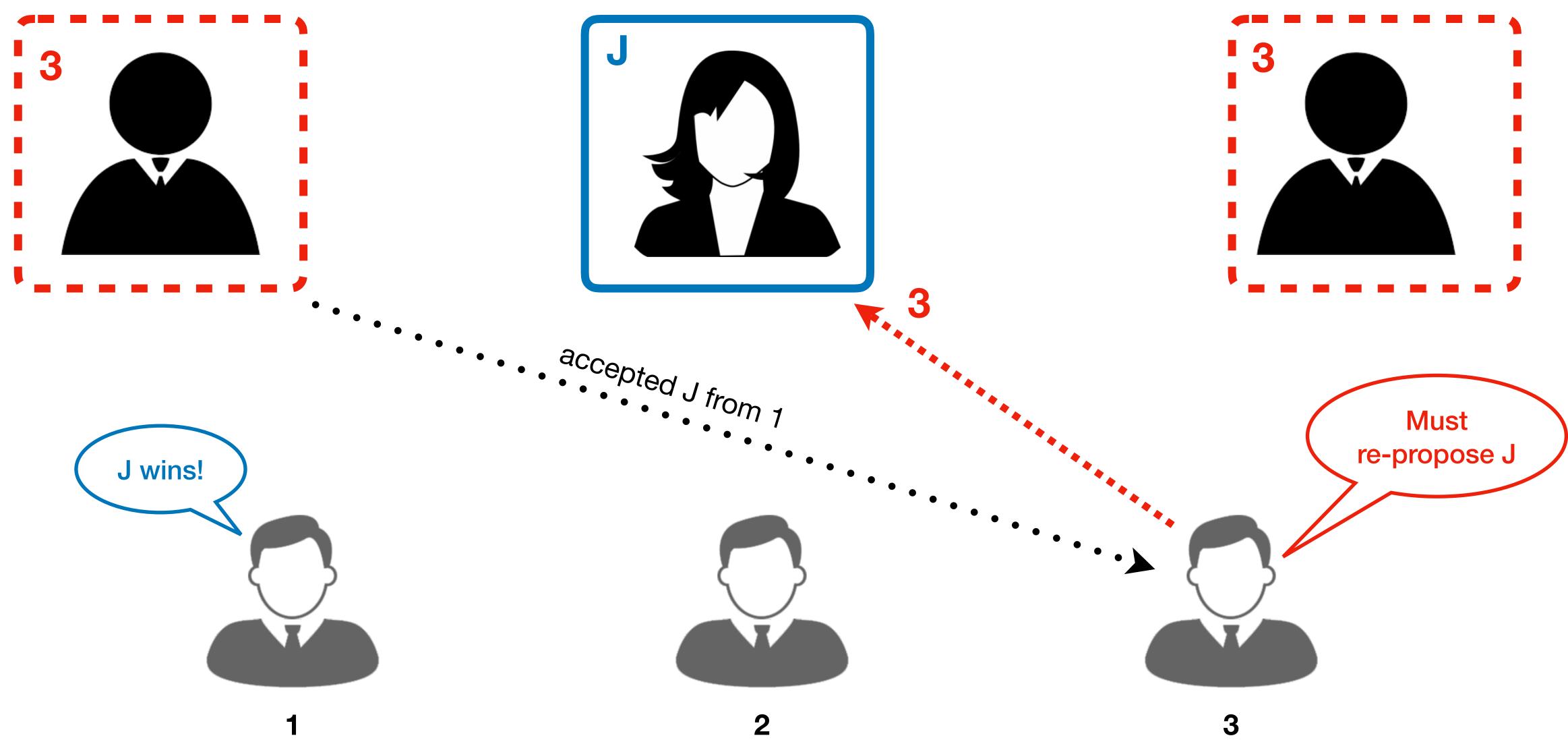
How to ensure irrevocability of consensus in the presence of *priorities* and *asynchrony*?

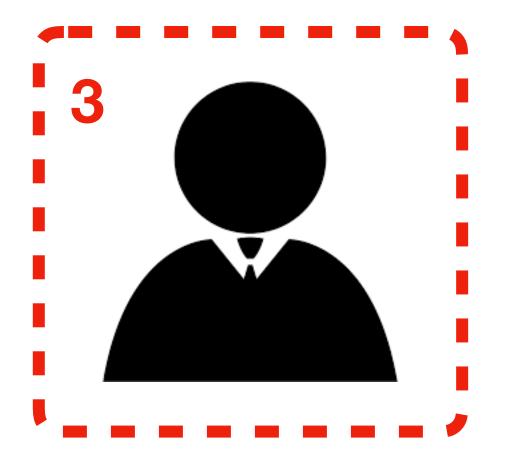
- Cooperation between Proposers and Acceptors:
 - Acceptors, when agreeing to support a proposer, *must* "tell" what was the *highest-ballot value* they have accepted;
 - Higher-ballot proposers re-propose already (partially) accepted values from the *lower-ballot* proposers, who secured the quorum before.
- This way, a proposer "knows" that, once it secured its quorum, either • its own proposal, or some higher-ballot one will be accepted • if its proposal got accepted, it will not be revoked

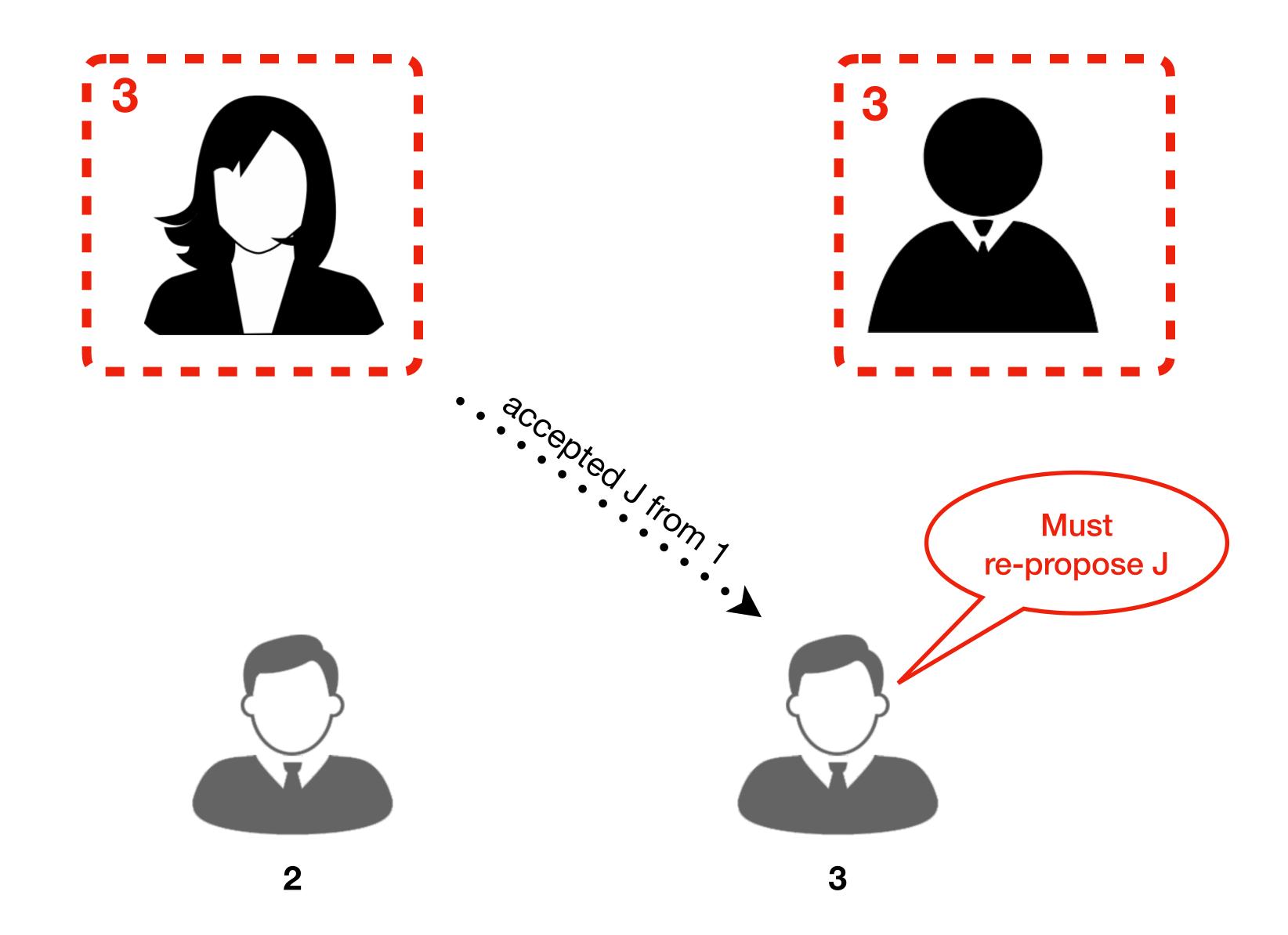
 - (thanks to quorum intersection)

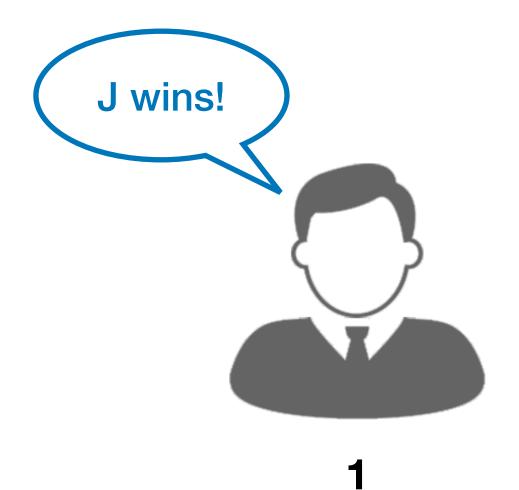
Key Idea 4

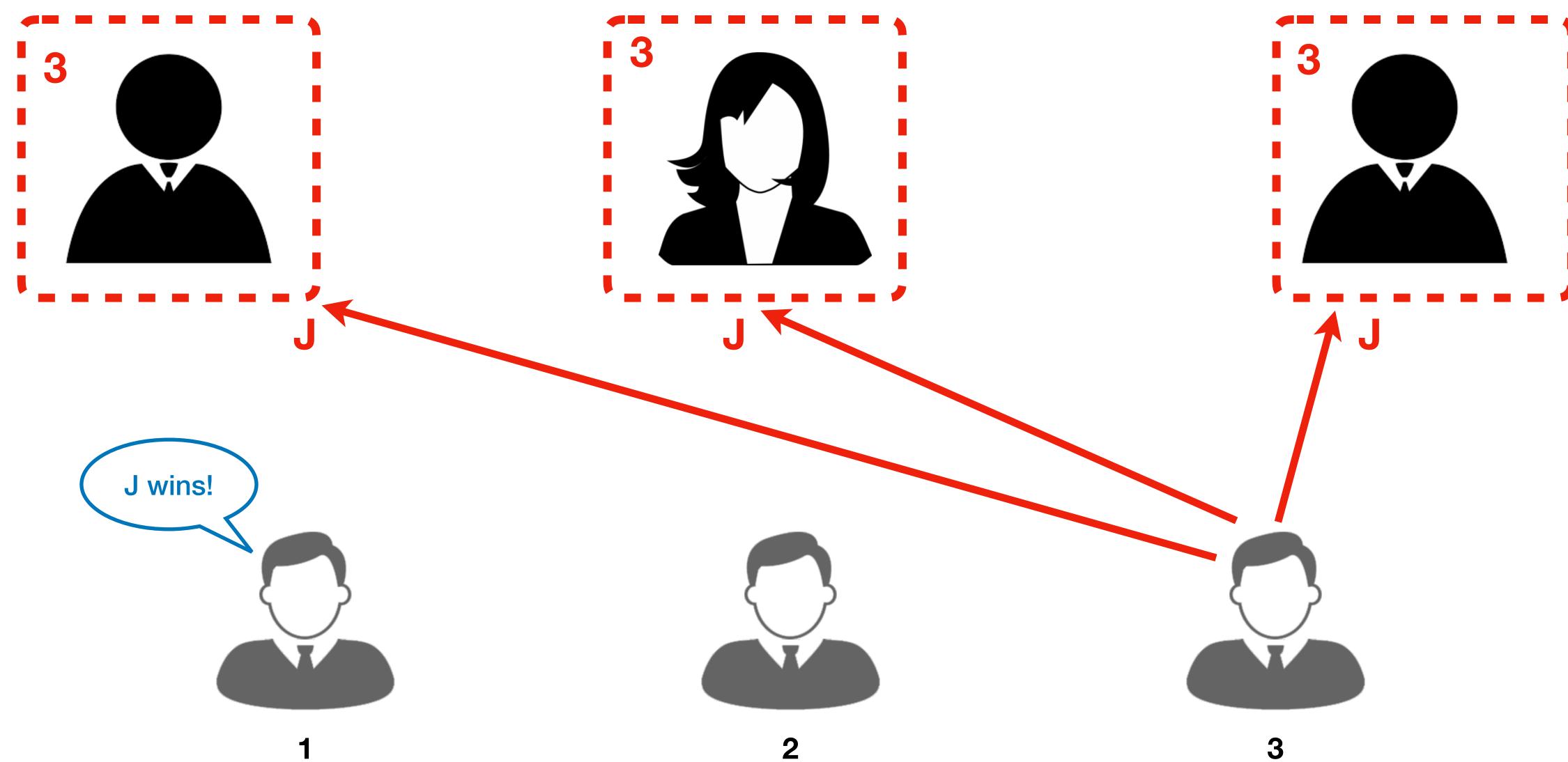


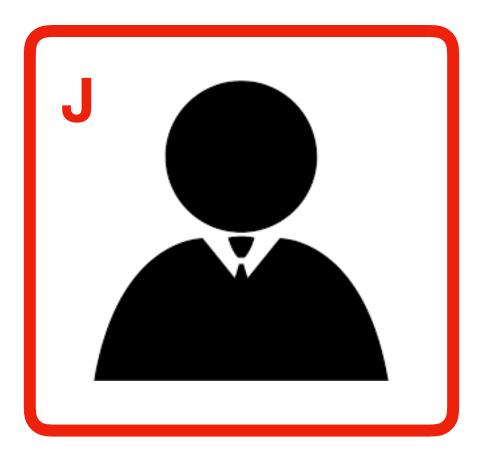


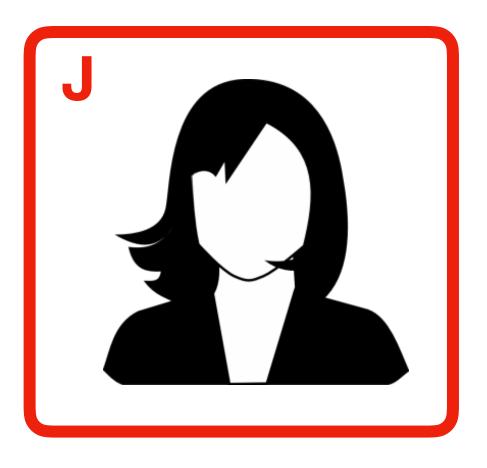


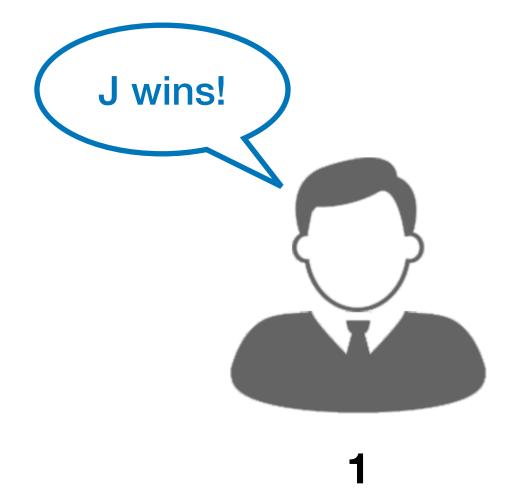


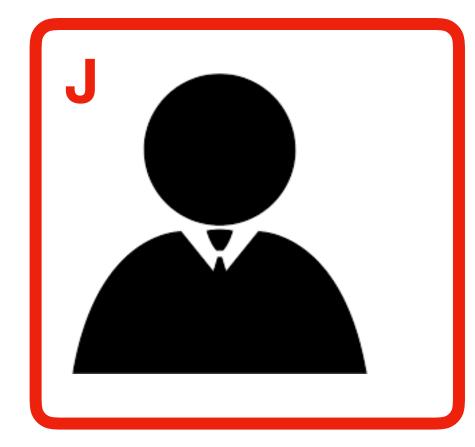




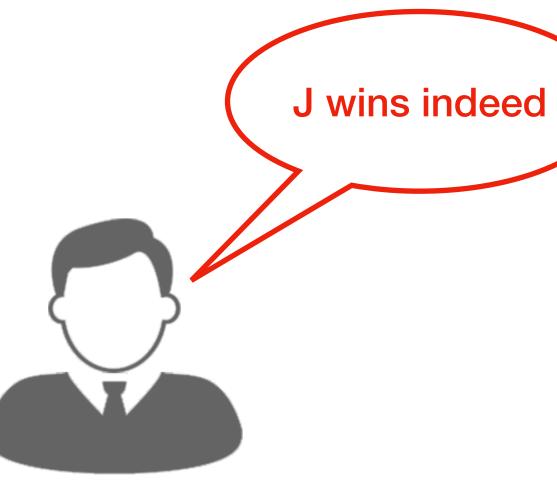






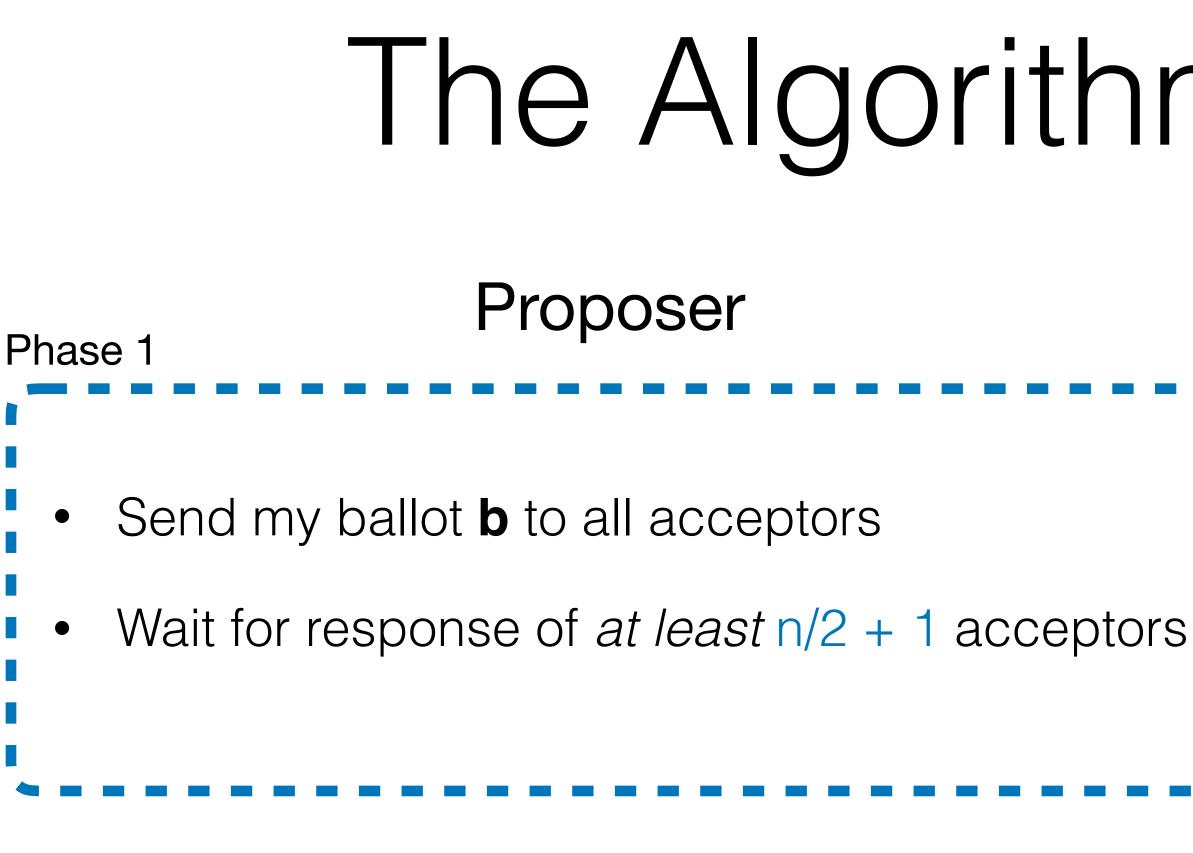






Two-Phase Ballot-based Consensus

- **Proposers** suggest values, acceptors decide upon acceptance;
- Each proposal goes in two rounds:
 - Phase 1: securing a quorum of acceptors for a proposal
 - Phase 2: sending out the proposal
- Acceptors agree only to support ballots higher than what they've seen;
- They inform proposers of previously accepted values, which those then re-propose.



- Phase 2
 - When heard back from n/2 + 1 acceptors, send them back (b, w), where
 - **b** is my ballot
 - w is the value from the acceptors with the highest ballot, or my own value.

The Algorithm in a Nutshell

Acceptor

• Upon receiving a **ballot b**

- if it's the first one, remember it and send "ok" back.
- if it's higher than b' we supported before, send back a previously accepted (b', v'), and remember
 b as what's currently supported.

Accept incoming value w if it comes with a ballot b, which we currently support; ignore otherwise.



Learning an Accepted Value

- Send request to all acceptors;
- value **v**, this is an accepted value.

• If at least n/2 + 1 acceptors respond back with the same

• Correctness of this reasoning follows from *irrevocability*.

- A practical fault-tolerant distributed consensus algorithm;
- Invented in 1990, published in 1998;
- Nowadays used everywhere: Google (Bigtable, Chubby), IBM, Microsoft;
- You have just seen it explained.

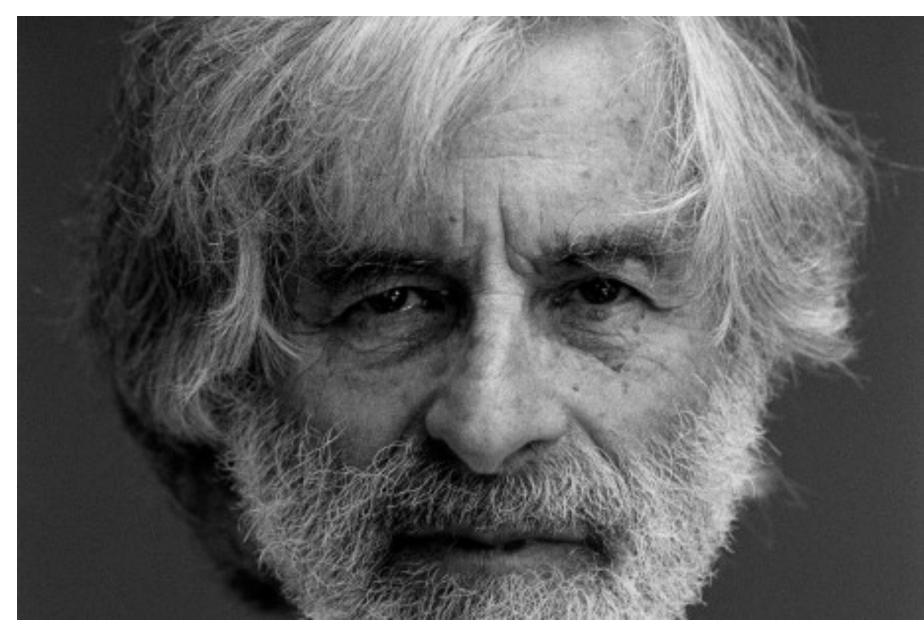


1990: Paxos first described

1998: Paxos paper published

2005: First practical deployments 2010: Widespread use! 2014: Lamport gets Turing Award

History of Paxos



Leslie Lamport (also known for LaTeX, Vector clocks, TLA) Turing Award winner 2014



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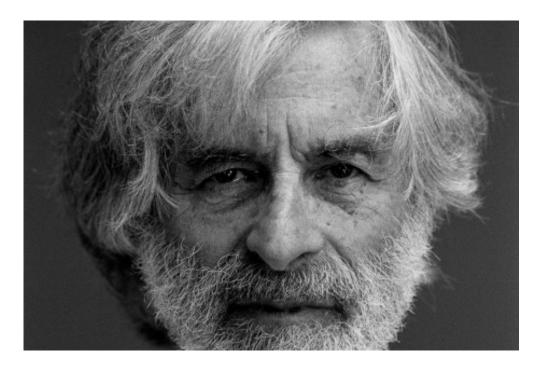
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Recent archaeological discoveries on the island of Paxos reveal that the parliament functioned despite the peripatetic propensity of its part-time legislators.

The legislators maintained consistent copies of the parliamentary record, despite their frequent forays from the chamber and the forgetfulness of their messengers

History of Paxos



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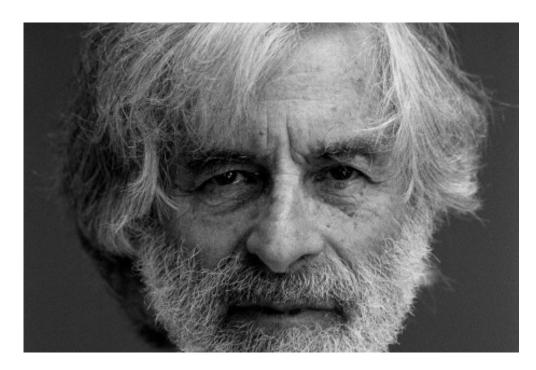
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- The ABCDs of Paxos [2001]
- **2005: Fi** Paxos Made Simple [2001]
- 2010: W Paxos Made Practical [2007]
 - Paxos Made Live [2007]
 - Paxos Made Moderately Complex [2011]
 - Paxos Consensus, Deconstructed and Abstracted [2018]

History of Paxos



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- Presented in the original Lamport's 1998 paper.
- Uses the described idea for a *sequence* of "slots" (think *transactions*).
- Includes reconfiguration (changing set of acceptors on the fly).
- Naive implementation: run Simple Paxos for each slot.
 - Better approach secure a quorum for several slots.

Multi-Paxos

Exploring the Paxos Zoo with Network Combinators

- A framework for combining different optimisations of Simple/Multi Paxos
- Written in Scala/Akka, available at https://github.com/certichain/network-transformations
- Accompanying paper:

```
val acceptorNum = 7
val learnerNum = 3
val proposerNum = 5
proposeValuesForSlots(slotValueMap, instance, factory)
Thread.sleep(400) // Wait for some time
learnAcceptedValues(slotValueMap, instance, factory)
```

Paxos Consensus, Deconstructed and Abstracted by García-Pérez et al, 2018.

def setupAndRunPaxos[A](slotValueMap: Map[Int, List[A]], factory: PaxosFactory[A]) {

val instance = factory.createPaxosInstance(system, proposerNum, acceptorNum, learnerNum)

Alternative Consensus Protocols

- View-Stamped Replication by Brian M. Oki and Barbara Liskov, 1989
- Raft by Diego Ongaro and John K. Ousterhout, 2014

Formal Verification of Consensus

- Initially only the *model* of the protocol was verified:
 - P. Kellomäki, 2004, Simple Paxos in PVS
 - M. Jaskelioff and S. Merz, 2005, Disk Paxos in Isabelle/HOL
 - O. Padon et al. 2017, Simple/Multi-Paxos in Ivy
- Verified runnable implementations came later:
 - V. Rahli et al., 2015, Multi-Paxos in EventML
 - C. Hawblitzel et al., 2015, Multi-Paxos in Dafny
 - J. Wilcox et al., 2015, Raft in Coq
 - C. Dragoi et al., 2016, (Synchronous) Simple Paxos in PSync
 - A. Pillai, 2018, Simple Paxos Coq (incomplete)

To Take Away

- Fault-Tolerant Consensus Protocols are a critical component of modern distributed systems and applications
- Consensus properties are *uniformity*, *non-triviality*, and *irrevocability*
- The key ideas of Lamport's Paxos protocol are:

 - Majority quorums (avoiding split brain and enabling fault-tolerance); • *Two-phase* structure (secure-commit);
 - Dichotomy and cooperation between proposers and acceptors.

To be continued...





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